Native Parallel Graphs
The Next Generation of Graph Database for Real-Time Deep Link Analytics
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Chapter 1

Modern Graph Databases

Graph databases are the fastest growing category in all of data management. Since seeing early adoption by companies including Twitter, Facebook and Google, graphs have evolved into a mainstream technology used today by enterprises in every industry and sector. By organizing data in a graph format, graph databases overcome the big and complex data challenges that other databases cannot. Graphs offer clear advantages over both traditional RDBMSs and newer NoSQL big data products.

A graph database is a data management software application. The building blocks are nodes (also known as vertexes or vertices) and edges (connections between nodes). A social graph is a simple example of a graph. To put this in context, a relational database is also a data management software application in which the building blocks are tables. Both require loading data into the software and using a query language or APIs to access the data.

Relational databases boomed in the 1980s. Many commercial companies (e.g., Oracle, Ingres, IBM) backed the relational model (tabular organization) of data management. In that era, the main data management need was to generate reports.

But the requirements for data management have changed. The explosive volume and velocity of data, more complex data analytics, frequent schema changes, real-time query response time, and more intelligent data
activation requirements have made people realize the advantages of the graph model.

Commercial software companies have been backing this model for many years, including TigerGraph, Neo4j, and DataStax’s DSE Graph. The technology is disrupting many areas, such as supply chain management, e-commerce recommendations, cybersecurity, fraud detection, and many other areas in advanced data analytics.

Key Benefits of a Graph Database

Any well-defined graph database has advantages over relational and NoSQL databases. In the following chapters, we’ll examine the differences between different graph databases.

Better, Faster Queries and Analytics

Graph databases offer superior performance for querying related data, big or small. The graph model offers an inherently indexed data structure, so it never needs to load or touch unrelated data for a given query. This efficiency makes it an excellent solution for better and faster real-time big data analytical queries. This is in contrast to NoSQL databases such as MongoDB, HBase/HDFS (Hadoop), and Cassandra, which have architectures built for data lakes, sequential scans, and the appending of new data (no random seek). The assumption in such systems is that every query touches the majority of a file. The situation is even worse in relational databases, which are slow at processing full tables and yet need to join tables together in order see connections.

Simpler and More Natural Data Modeling

Anyone who has studied relational database modeling understands the strict rules for satisfying database normalization and referential integrity. Some NoSQL architectures go to the other extreme, pulling all types of data in one massive table. In a graph database, on the other hand, you are free to define whatever node types you want, and free to define edge types to represent relationships between vertices. A graph model has exactly as much semantic meaning as you want, with no normalization and no waste.

Represent Knowledge and Learn More

Knowledge graphs are, of course, graphs. A knowledge graph is an assemblage of individual facts represented in the form <subject><predicate><object>, such as <Pat><owns><boat>. With <subject> and <object> as nodes and <predicate> as the edge between them, you have a graph. The real power of a knowledge graph is to see the big picture: follow a chain of edges, analyze a neighborhood, or analyze the entire graph. From that, you can deduce or infer new relationships.

Object-Oriented Thinking

In a graph, each node and edge is a self-contained object instance. In a schema-based graph database, the user defines node types and edge types, just like object classes. Moreover, the edges which connect a node to others
are somewhat like object methods, because they describe what the node can “do.” To process data in a graph, you “traverse” the edges, conceptually traveling from node to adjacent node, maintaining the integrity of the data. In a relational database, in contrast, to connect two records, you must join them and create a new type of data record.

**More Powerful Problem-Solving**

Graph databases solve problems that are both impractical and practical for relational queries. Examples include iterative algorithms such as PageRank, gradient descent, and other data mining and machine learning algorithms. Some graph query languages are Turing complete, meaning that you can write any algorithm on them. There are many query languages in the market that have limited expressive power, though.

**Modern Graph Databases Offer Real-Time Speed at Scale**

As stated above, graph databases offer better modeling which in turn leads to better problem-solving for interconnected data. But a historical weakness of graph databases has been poor scalability: they cannot load or store very large datasets, cannot process queries in real time, and/or they cannot traverse more than two connections in series (two hops) in a query.

However, a new generation of graph database is now available. Based on Native Parallel Graph architecture, this 3rd generation graph has the speed and scalability to provide the following benefits:

**Concurrent Querying and Data Updates in Real-Time**

Many past graph systems could not ingest new data in real-time, because they were built on NoSQL data stores designed for good read performance at the cost of write performance. But many applications, such as fraud detection and personalized real-time recommendation, and any transactional or streaming data application, demand real-time updates. Native Parallel Graphs handle both read and write in real-time. Typically the parallelism is coupled with concurrency control to provide high queries-per-second for both read queries and graph updates.

**Deep Link Analytics**

One of the most important gains achieved by Native Parallel Graph design is the ability to handle queries that traverse many, many hops, 10 or more, on very large graphs and in real time. The combination of the native graph storage (which makes each data access faster) and parallel processing (which handles multiple operations at the same time) transforms many use cases from impossible to possible.

**Dynamic Schema Change**

In principle, a graph model lets you describe new types of data and new types of relationships by simply defining new node types and edge types. Or you may want to add or subtract attributes. You can connect multiple datasets by simply loading them together any adding some new edges to connect them. The ease with which this can be done varies in practice. Native Parallel Graphs, because they are graphs from the ground up and are designed with
graph schema evolution in mind, can handle such schema changes dynamically — that is, while the graph remains in use.

**Effortless Multidimensional Representation**

Suppose you want to add geolocation attributes to entities. Or you want to record time series data. Of course you can do this with a relational database. But with a graph database, you can choose to treat Location and Time as node types as well as attributes. Or you can use weighted edges to explicitly link entities that are close together, in space or time. You can create a chain of edges to represent a causal change. Unlike the relational model, you do not need to create a cube to represent multiple dimensions. Every new node type and edge type represents a potential new dimension; actual edges represent actual relationships. The possibilities are endless.

**Advanced Aggregation and Analytics**

Native Parallel Graph databases, in addition to traditional group-by aggregation, can do more complex aggregations that are unimaginable or impractical in relational databases. Due to the tabular model, aggregate queries on a relational database are greatly constrained by how data are grouped together. In contrast, the multi-dimensional nature of graphs and the parallel processing of modern graph databases let the user efficiently slice, dice, rollup, transform, and even update the data — without the need to preprocess the data or force it into a rigid schema.

**Enhanced Machine Learning and AI**

We have already mentioned that graphs can be used as knowledge graphs, which allow one to further infer indirect facts and knowledge. Moreover, any graph is a powerful asset for better machine learning. First, for unsupervised learning, the graph model provides an excellent way to detect clusters and anomalies, because you just need to pay attention to the connections. For supervised learning, which is always hungry for more and better training data, graphs provide an excellent source of previously overlooked features. For example, simple features such as the outdegree of an entity or the shortest path between two entities could provide the missing piece to boost predictive accuracy. Then if the machine-learning/AI application requires real-time decision-making, we need a fast graph database. The keys to a successful graph database to serve as a real-time AI data infrastructure are:

- Support for real-time updates as fresh data streams in
- A highly expressive and user-friendly declarative query language to give full control to data scientists
- Support for deep-link traversal (>3 hops) in real-time (sub-second), just like human neurons sending information over a neural network
- Scale out and scale up to manage big graphs

There are many advantages of native graph databases managing big data that cannot be worked around by traditional relational databases. However, as any new technology replacing old technology, there are still obstacles in adopting graph databases. This includes the non-standardization of the graph database query language. There have been incomplete offerings that have led to subpar performance and subpar usability, which has slowed down
Comparing Graphs and Relational Databases

Storage Model

An RDBMS stores information in tables (rows/columns). Typically, there is a table for each type of entity (e.g., Student, Instructor, Course, Semester, Registration). In the real world, there could be dozens or even hundreds of tables in an RDBMS.

In a graph database, all information is stored as a collection of nodes and edges (connections between nodes), not in physically separated tables. For example, a user can be represented as a node which is directly connected to several other nodes: the user’s phone number, home address, purchased products, friends, etc. Each node and each edge can store a set of attributes.

Query Model

The RDBMS fundamental computational model is based on scanning rows, joining rows, filtering rows, and aggregation.

A graph database’s computational model is based on starting from an initial set of nodes and traversing the graph in a series of hops. Each hop moves from the current set of nodes and follows a selected subset of connections (edges) to their neighboring nodes. The query’s details specify where to start, which edges and destination nodes to select, how many hops to take, and what to do with the data observed during the traversal.

Types of Analytics

Relational databases are good at accounting, simple data lookup that involves one, two, or at most three tables, and descriptive statistics. However, they are not well-suited for more discovery- or prediction-oriented analytics. For example, it’s hard or impossible to write a SQL query to answer questions like “How are these three users connected?”, “How much money eventually flows from an account A to another 3 accounts?”, “What is the shortest/cheapest route between Point A and Point B?”, or “What is the downstream consequences if a component C in a network is out of service?” In a graph database system, all the above types of analytics can be naturally and efficient expressed and solved.

Real-Time Query Performance

In a relational database, each table is stored physically separately, so following a connection from one table to table is relatively slow. Moreover, if the database designer did not index their foreign keys, following the connections will be VERY slow. In a graph database, everything about a node is connected to the node already, thus the query performance can be significantly faster.
Transitioning to a Graph Database

With the Tigergraph native parallel graph database, setting up a basic graph schema and loading data into it are very simple. If you already have a well-normalized relational schema, it is trivial to convert it to a workable graph schema. After all, your entity-relationship model is a graph, right? The most challenging step will be learning to think about your problem solving (querying) from a graph perspective (based on traversing from node to node) instead of from a relational perspective (based on joining tables, projecting, and grouping to provide an output table). For many applications, it is actually more natural and intuitive to think in the graph world, especially when all information are already connected together in a graph.

TigerGraph provides GraphStudio UI, a complete end-to-end SDK, as well as GSQL, a high level language to make developing a solution on top of the TigerGraph platform as smooth as possible and to make the steps very compatible with the SQL world. You can follow this three-step process:

1. Create a graph model (very similar to SQL “create table”)
2. Load initial data into graph (simple declarative statements if your data is tabular)
3. Write a graph solution using GSQL. The syntax is modeled after SQL, enhanced with concepts from high level procedural languages and MapReduce.

The knowledge and skills from the RDBMS domain are transferable to the TigerGraph world, especially in the first two steps. TigerGraph’s extensive documentation and training materials provides numerous examples from various verticals and use cases to illustrate these three steps, applied to cases such as collaborative filtering recommendation, content-based recommendation, graph algorithms like PageRank, and fraud investigation. You will see that the direct translation of the relational schema to graph schema is not always the best choice.

Moreover, in the TigerGraph system, the graph is also a distributed computational model: you can associate a compute function with nodes and edges. Logically, nodes and edges aren't just pieces of static data anymore; they become active computing elements, similar to neurons in our brains. Nodes can send messages to other nodes via edges. Once you learn to “think like a graph”, a new world of possibilities will be open to you.
Chapter 2

The Graph Database Landscape

Graph databases are the fastest growing category in all of data management, according to consultancy DB-Engines.com. A recent Forrester survey showed that 51 percent of global data and analytics technology decision-makers are employing graph databases.

All other database types (RDBMS, data warehouse, document DB, and key-value DB) started primarily on-premises and were welcomed before database-as-a-service was established. Now that the large cloud service providers are going all in on graph technology, graph database adoption is likely to keep accelerating.

Many different kinds of graph database offerings are available today and each offers unique features and capabilities, so it’s important to understand the differences.

Operational Graph Databases

According to Gartner, Operational Databases (not limited to graph databases) are “DBMS products suitable for a broad range of enterprise-level transactional applications, and DBMS products supporting interactions and observations as alternative types of transactions.” (Gartner Inc., Magic Quadrant for Operational Database Management Systems, published: October 2016, ID: G00293203). Bloor Research states these solutions may be either native graph stores or built on top of a NoSQL platform. They are focused at transactions (ACID) and operational analytics, with no absolute requirement for indexes. (Bloor Research: Graph and RDF databases 2015 #2, published Sept. 2015)

Operational Graph Databases include Titan, JanusGraph, OrientDB, and Neo4j.
Knowledge Graph / RDF

The Resource Description Framework (RDF) is a family of World Wide Web Consortium specifications originally designed as a metadata model. It has come to be used as a general method for conceptual description or modeling of information that is implemented in web resources, using a variety of syntax notations and data serialization formats. Each individual fact is a triple (subject, predicate, object), so RDF databases are sometimes called triplestores.

According to Bloor Research, these graphs are often semantically focused and based on underpinnings (including relational databases). They are ideal for use in operational environments, but have inferencing capabilities and require indexes even in transactional environments. (Bloor Research: Graph and RDF databases 2015 #2, published Sept. 2015)

A number of graph database vendors have based their knowledge graph technology on RDF, including AllegroGraph, Virtuoso, Blazegraph, Stardog, and GraphDB.

Multi-Modal Graphs

This category encompasses databases designed to support more than one model types. For example, a common possibility is a three-way option of document store, key value store or RDF/graph store. (Bloor Research: Graph and RDF databases 2016, published Jan. 2017) The advantages of a multi-modal approach are that different types of queries, such as graph queries and key-value queries can be run against the same data. The main disadvantage is that the performance cannot match a dedicated and optimized database management system.
Examples of multi-modal graphs include Microsoft Azure Cosmos DB, ArangoDB and DataStax.

**Analytic Graphs**

Bloor Research states that analytic graphs focus on solving ‘known knowns’ problems (the majority) – where both entities and relationships are known, or on ‘known unknowns’ and even ‘unknown unknowns.’ The research firm says, “Multiple approaches characterize this area with different architectures including both native and non-native stores, different approaches to parallelisation, and the use of advanced algebra.” (Bloor Research: Graph and RDF databases 2015 #2, published Sept. 2015)

Examples of Analytic Graphs include Apache Giraph, Spark GraphX, and Turi (formerly GraphLab, now owned by Apple).

**Real-time Big Graphs**

A new category of graph databases, called the real-time big graph, is designed to deal with massive data volumes and data ingestion rates and to provide real-time analytics. To handle big and growing datasets, real-time big graph databases are designed to scale up and scale out well.

Real-time big graphs enable real-time large graph analysis with both 100M+ node or edge traversals/sec/server and 100K+ updates/sec/server, regardless of the number of hops traversed in the graph. They also provide real-time graph analytic capabilities to explore, discover, and predict very complex relationships. This represents Real-Time Deep Link Analytics - achieving 10+ hops of traversal across a big graph, along with fast graph traversal speed and data updates.

Examples of Real-Time Big Graphs include TigerGraph.

**Making Sense of the Offerings**

In summary, there are many different kinds of graph database offerings available today and unique advantages to each, which is why it’s important to understand the differences as graph databases continue to see adoption by enterprises across every vertical and also use case. Per a recent Forrester Research survey, “51 percent of
As organizations embrace the power of the graph, knowing offerings available and their advantages is important to determine the best option for a particular use case. Demonstrated by the Real-Time Big Graphs category, graph technology is evolving into the next-generation. These solutions are specifically designed to support real-time analytics for organizations with massive amounts of data.
Chapter 3

Real-time Deep Link Analytics

Graph databases offer an ideal model for analyzing and answering complex questions pertaining to the relationships and connections among large data sets. However, their effectiveness at delivering real-time insights depends on a key feature: the number of hops (i.e., the degrees of separation) which can be traversed in real-time in a big graph.

Graphs overcome the challenge of representing massive, complex and interconnected data by storing data in a format that includes nodes, edges and properties. They offer several advantages over traditional RDBMS and newer big data products, including better suitability for relationship analysis. However, big graph analytics requires not only the right storage, but also the ability to access and process massive graph data quickly.

Traditional graph technologies have not fulfilled the promise of real-time analytics because they cannot support three or more hops of traversal for big graphs. They can handle multiple hops on small graphs (with a few million nodes and edges), but their ability to handle consecutive hops drops precipitously as the graph size grows. Other limitations include trouble loading large quantities of data and poor ingestion of data in real-time.

With increasing real-time data so prevalent in enterprise ecosystems, it’s time for graph databases to grow up.
Introducing Real-time Deep Link Analytics

Today's enterprises demand real-time graph analytic capabilities that can explore, discover, and predict complex relationships. This represents Real-Time Deep Link Analytics which is achieved utilizing three to 10+ hops of traversal across a big graph, along with fast graph traversal speed and fast data updates.

Consider a simple personalized recommendation such as “customers who liked what you liked also bought these items.” Starting from a person, the query first identifies items you've viewed / liked / bought.

Second, it finds other people who have viewed / liked / bought those items.

Third, it identifies additional items bought by those people.

Person → Product → (other) Persons → (other) Products

This query requires three hops in real time, so it is beyond the two-hop limitation of previous generations of graph technology on larger data sets. Adding in another relationship (e.g, features of products, availability of products) easily extends the query to four or more hops.

Examples of Real-time Deep Link Analytics

As each additional hop reveals new connections and hidden insight from within colossal amounts of data, Real-Time Deep Link Analytics represents the next stage and evolution of graph analytics. In particular, Real-Time Deep Link Analytics offers huge advantages for use cases including fraud prevention, personalized recommendation, supply chain optimization, and other analysis capabilities needed for today's most critical enterprise applications. Here's a look at how:

Risk & Fraud Control

Real-Time Deep Link Analytics combats financial crime by identifying high-risk transactions. For example, starting from an incoming credit card transaction, how this transaction is related to other entities can be identified as follows:

New Transaction → Credit Card → Cardholder → (other) Credit Cards → (other) Bad Transactions

This query uses four hops to find connections only one card away from the incoming transaction. Today's fraudsters try to disguise their activity by having circuitous connections between themselves and known bad activity or bad actors. Any individual connecting the path can appear innocent, but if multiple paths from A to B can be found, the likelihood of fraud increases. Thus not only depth of traversal (4 hops) is needed, but also breadth of traversal (finding multiple paths).
Given this, successful risk and fraud control requires the ability to traverse several hops. This traversal pattern applies to many other use cases — where you can simply replace the transaction with a web click event, a phone call record or a money transfer. With Real-Time Deep Link Analytics, multiple, hidden connections are uncovered and fraud is minimized.

**Multi-Dimensional Personalized Recommendations**

Real-Time Deep Link Analytics enables queries to find similar customers or to provide personalized recommendations for products. Consider the following examples of recommendation paths, all of which are longer than three hops:

```
Person→ Purchases→ Products→ (other)Purchases→ (other)Persons→ (other)Products
Person → Purchases→ Products→ Categories→ (other)Products
Person→ Clicks→ Products→ Categories→ (other)Products
```

Any of the above paths can be used for personalized recommendations on a retail website, for example, either individually or in combination with each other. The first path selects products bought by other users who bought the same products you bought. The second determines products similar to the products you bought, and the third determines products similar to the products you viewed/are interested in. A recommendation algorithm can assign different weights at run time to products found in each type of path to give a user a mixed ensemble of products for recommendation.

However, due to limitations in current systems, the vast majority of current recommendation functions use offline computation. As recommendations are computed in the background they are unable to perform real-time, on-demand analytics using the latest data. This has been a setback that new graph database technology is now able to address.

**Power Flow Optimization, Supply-Chain Logistics, Road Traffic Optimization**

These applications adjust each entity and/or each connection, until a dynamic equilibrium or optimization is established. For example, in a national or regional power grid, the power output of each generator is adjusted as follows:

```
All Entities:
→ relationship to and effect on neighbors
→ Update All Entities
<repeat until a stable state is achieved>.
```
Finding the right values inherently requires iterative computation in a graph (similar to PageRank) until some metric values converge. Moreover, each top-level component (e.g., a power generator), is the hub for a network of supporting elements, resulting in a multi-tier mesh. A power distribution network could easily have a six-hop path.

```
Power generator→ Transformers→ Control units→ Lower-level transformers→ Lower-level control units→ Meters→ Power-consuming devices
```

Real-Time Deep Link Analytics is needed for a graph database system to handle this level of computation.

### A Transformational Technology for Real-time Insights and Enterprise AI

What enterprises currently get from limited graph analytics is only the tip of iceberg compared to what Real-Time Deep link Analytics can provide. By supporting all connections between data entities, Real-Time Deep Link Analytics offers a truly transformative technology, particularly for organizations with colossal amounts of data.

The entry of Real-Time Deep Analytics represents a new era of graph analytic technology. As the next stage in the graph database revolution, it is empowering users to explore, discover and predict relationships more accurately, more quickly and with more insight than ever before. The result is real-time support for enterprise AI applications – a true game changer in today’s competitive market moving at the pace of now.
Chapter 4

Differentiating Between Graph Databases

Graph databases have gotten much attention due to their advantages over relational models. With many vendors rushing into this area, it is becoming challenging to evaluate all the product offerings. Here is a list of what to consider when evaluating graph databases.

- **Property graph or RDF store.** RDF stores are specialty graph databases; property graphs are general purpose. If your data are purely RDF and if your queries are limited to pattern matching or logical inference, then you may be satisfied with an RDF database. Other users should focus on property graphs. Even so, some enterprises with RDF knowledge graph applications have still turned to property graph databases, because the performance of the available RDF databases was not strong enough.

- **Loading capability.** If you measure data in gigabits or larger, this is a critical differentiator. It is especially important if you plan to routinely import different data from your data lake into your graph DB. Both loading speed and usability are important. If you do not already have test data, consider a public data set such as the 1.5B edge Twitter follower network ([http://an.kaist.ac.kr/traces/WWW2010.html](http://an.kaist.ac.kr/traces/WWW2010.html)) or the 1.8B edge Friendster network ([http://snap.stanford.edu/data/com-Friendster.html](http://snap.stanford.edu/data/com-Friendster.html)). First, does the graph database require that you define a schema beforehand and if so, it is straightforward? Does it support the data types, including composite types, that you need? Can the DB directly extract, transform, and load (ETL) data from your data files, or do you need to preprocess your data? Can it handle multiple common input file formats? How long does it take to load 10M edges? 20M edges? Does the database maintain good loading speed as the graph grows? Does it support parallel loading, for better throughput? Does it support scheduling and restart, which may be necessary for very large loading jobs? These questions will jump-start your evaluation.

- **Native graph storage.** Many graph databases are non-native, meaning they store graph data in relational tables, RDF triples, or key-value pairs on disk. When data are fetched to memory, they provide middle layer APIs to simulate a graph view and graph traversal. In contrast, native graph databases store data directly in a graph model format—nodes and edges. The most well-known examples of native graphs are TigerGraph and Neo4j. Non-native graphs are a compromise solution. They can more easily support a multi-modal database (presenting more than data model from one data store), by sacrificing graph performance. On the other hand, the edge-and-node storage model of a native graph provides built-in indexing, for quicker and more efficient graph traversal. When the dataset is large, non-native graphs generally have difficulty handling queries with 3 or more hops.

- **Schema or schema-less.** Some graph databases claim they do not require a pre-defined schema. Other
graph databases require a predefined schema, following the model of traditional relational databases. It may seem like schema-less is better (less work for the architect!) but there is a price in performance. A predefined schema allows for more efficient storage, query processing, and graph traversal, so the small initial effort to define a schema pays for itself many times over. However, if a predefined schema is required, be sure that the database supports schema changes (preferably online, while the database is in service). You can be sure that the initial schema you design will not be your final schema.

- **OLTP, OLAP, or HTAP.** What type of operations do you want your graph database to perform? Some graph platforms are purely for large-scale processing (OLAP), such as PageRank or community detection. A good OLAP graph database should have a highly parallel processing design and good scalability. Some graph databases are designed for “point queries” - starting from one or a few nodes and traversing for a few hops. To be a truly transactional database (for OLTP), however, it should support ACID transactions, concurrency, and a high number of queries per second (QPS). If the transactions include database updates, then real-time updates is a must (see below). A very few graph databases satisfy both of these requires and so can be considered Hybrid Transactional/Analytical Processing (HTAP) databases.

- **Real-time update.** Real-time update means that a database update (add, delete, or modify) can happen at the same time as other queries on the database, and also that the update can finish (commit) and be available quickly. Common graph update operations include insertion/deletion of a new node/edge and update of an attribute of an existing node/edge. Ideally, real-time update should be coupled with concurrency control, such that multiple queries and updates (transactions) can run simultaneously, but the end results are the same as if the transactions had run sequentially. Most non-native graph platforms (e.g., GraphX, DataStax DSE Graph) do not support real-time update due to the immutability of their data storage systems (HDFS, Cassandra).

- **Real-time deep-link analytics.** On most graph databases today, query response time degrades significantly starting from three hops. Yet the real value of a graph database is to find those non-superficial connections which are several hops deep. A simple way to check a graph database’s deep link performance is to run a series of k-hop neighborhood size queries for increasing values of k, on a large (~1B edge) graph. That is, find all the nodes which are one hop away from a starting node, then two hops, three hops, and so on. To focus on graph traversal and not on IO time, return only the number of k-hop neighbors.

- **Scalability with performance.** Scalability is an important feature in the Big Data era. There is always more data out there, and the more/richer/fresher data you have, the better analytics and insights you will be able to produce. Users need assurance that their database will be able to grow. Database scalability can be broken down into three main concerns:
  - **Software support** - Are there software limits to the number of entities or size of data that can be managed?
  - **Hardware configuration** - Can the database take advantage of increased hardware capacities on a single machine (scale up)? Can the database be distributed across an ever-growing cluster of
machines (scale out)?

- **Scale-up performance** - In a perfect system, if the data, memory and disk space all increase by a factor of S, then the full graph loading time should increase by a factor of S, point query QPS should remain about the same, and analytic (full graph) query time should increase according to the algorithm’s computational complexity. That is, we expect things to run slower, but only due to the fact that there is more data to process.

- **Scale-out performance** - In a perfect system, if the data and number of machines both increase by a factor of S, then full graph loading time should remain constant (more data and more machines cancel each other out), the point query QPS should increase by up to S (an improvement), and the analytic (full graph) query time should increase according to the algorithm’s computational complexity, divided by S. For example, if a graph grows to have 2x edges on 2x machines, PageRank ideally takes the same amount of time, because PageRank’s computational effort scales with the number of edges. Because machine-machine data transfer is slower than intra-machine transfer, no system achieves this perfect mark, but you can compare systems to see how close they come to the ideal standard. Note: Some databases with good parallel design can scale with the number of cores in a CPU. This is technically scale-up, but its behavior is more similar to that of scale-out.

- **Enterprise Requirements.** Besides the basic features of the graph database itself, enterprises need support for security, reliability, maintenance, and administration. Many of these requirements are identical to the requirements for traditional databases: role-based access control, encryption, multiple tenancy, high availability, backup and restore, etc. However, since the graph database market is less mature, not all vendors have a comprehensive set of enterprise features. Customers may be willing to be flexible for some of these requirements to obtain the unique advantages of graph databases.

- **Graph Visualization.** A final factor here is one that is unique to graph databases: the ability to display a graph, either as an included capability or supported by a third party tool. A good visual display greatly aids in the interpretation of the data. How large a graph can be displayed, and how is the layout determined? Does the visualization system also support graph exploration or querying?

Graph databases are hot, so the market is offering consumers many choices. Regardless of your requirements, considering each of the factors above will help you select the right graph database system.
Chapter 5

Native Parallel Graphs

Different Architectures Support Different Use Cases

Whether for customer analytics, fraud detection, risk assessment, or another real-world challenge, the ability to quickly and efficiently explore, discover and predict complex relationships is a huge competitive differentiator for businesses today. Getting it done involves more than merely having connected data – it’s about real-time and up-to-date correlation, detection and discovery. Organizations need to be able to transform structured, semi-structured and unstructured data and massive enterprise data silos into an intelligent, interconnected, and operational data network that can reveal critical patterns and insights to support business goals.

This elemental pain point – the need for real-time analytics for enterprises with enormous volumes of data – is fueling graph databases’ emergence as a mainstream technology being embraced by companies across a broad range of industries and sectors.

Since seeing early adoption by companies including Twitter, Facebook and Google, graph databases are heating up. Giant cloud service providers Amazon, IBM and Microsoft have added graph databases in the last two years, validating the industry’s growing interest in graph technology for easy and natural data modeling, easy-to-write queries to solve complex problems, and fast insights from interconnected data.

Graph databases excel at answering complex questions about relationships in large data sets. But most of them hit a wall—in terms of both performance and analysis capabilities—when the volume of data grows very large, or the problem needs deep link analytics, or when the answers must be provided in real time.

That’s because earlier generations of graph databases lack the technology and design for today’s speed and scale requirements. First generation designs (such as Neo4j) were not built with parallelism or distributed database concepts in mind. The second generation is characterized by creating a graph view on top of a NoSQL store. These products can scale to large size, but the added layer robs them of much potential performance. It is costly to perform multi-hop queries without a native graph design, and many NoSQL platforms are designed for read performance only. They do not support real-time updates.

TigerGraph represents a new generation in graph database design - the native parallel graph, overcoming the limitations of earlier generations. Native parallel graph enables deep link analytics, which offers the following advantages:

- Faster data loading to build graphs quickly
- Faster execution of graph algorithms
- Real-time capability for streaming updates and insertions
- Ability to unify real-time analytics with large-scale offline data processing
- Ability to scale up and scale out for distributed applications

**Graph Traversal: More Hops, More Insight**

Why deep link analytics? Because the more links you can traverse (hop) in a graph, the greater the insight you achieve. Consider a hybrid knowledge and social graph. Each node connects to what you know and who you know. Direct links (one hop) reveal what you know. Two hops reveal everything that your friends and acquaintances know. Three hops? You are on your way to revealing what everyone knows.

The graph advantage is knowing the relationships between the data entities in the data set, which is the heart of knowledge discovery, modeling, and prediction. Each hop can lead to an exponential growth in the number of connections and, accordingly, in the amount of knowledge. But therein lies the technological hurdle. Only a system that performs hops efficiently and in parallel can deliver real-time deep link (multi-hop) analytics.

In Chapter 3, we took a detailed look at real-time deep link analytics and some of the use cases where it adds unique value: risk and fraud control, personalized recommendations, supply chain optimization, power flow optimization, and others.

Having seen the benefits of a native parallel graph, now we’ll take a look at how it actually works.

**TigerGraph’s Native Parallel Graph Design**

The ability to draw deep connections between data entities in real time requires new technology designed for scale and performance. Not all graph databases claiming to be native or to be parallel are created the same. There are many design decisions which work cooperatively to achieve TigerGraph’s breakthrough speed and scalability. Below we will look at these design features and discuss how they work together.

**A Native Distributed Graph**

TigerGraph is a pure graph database, from the ground up. Its data store holds nodes, links, and their attributes, period. Some graph database products on the market are really wrappers built on top of a more generic NoSQL data store. This virtual graph strategy has a double penalty when it comes to performance. First, the translation from virtual graph operation to physical storage operation introduces extra work. Second, the underlying structure is not optimized for graph operations. Moreover, the database is designed from the beginning to support scale out.
Compact Storage with Fast Access

TigerGraph isn’t described as an in-memory database, because having data in memory is a preference but not a requirement. Users can set parameters that specify how much of the available memory may be used for holding the graph. If the full graph does not fit in memory, then the excess is stored on disk. Best performance is achieved when the full graph fits in memory, of course.

Data values are stored in encoded formats that effectively compress the data. The compression factor varies with the graph structure and data, but typical compression factors are between 2x and 10x. Compression has two advantages: First, a larger amount of graph data can fit in memory and in CPU cache. Such compression reduces not only the memory footprint, but also CPU cache misses, speeding up overall query performance. Second, for users with very large graphs, hardware costs are reduced. For example, if the compression factor is 4x, then an organization may be able to fit all its data in one machine instead of four.

Decompression/decoding is very fast and transparent to end users, so the benefits of compression outweigh the small time delay for compression/decompression. In general, decompression is needed only for displaying the data. When values are used internally, often they may remain encoded and compressed.

Internally hash indices are used to reference nodes and links. In Big-O terms, our average access time is O(1) and our average index update time is also O(1). Translation: accessing a particular node or link in the graph is very fast, and stays fast even as the graph grows in size. Moreover, maintaining the index as new nodes and links are added to the graph is also very fast.

Parallelism and Shared Values

When speed is your goal, you have two basic routes: Do each task faster, or do multiple tasks at once. The latter avenue is parallelism. While striving to do each task quickly, TigerGraph also excels at parallelism, employing an MPP (massively parallel processing) design architecture throughout. For example, its graph engine uses multiple workers and threads to traverse a graph, and it can employ each core in a multicore CPU.

The nature of graph queries is to “follow the links.” Start from one or more nodes. Look at the available connections from those nodes and follow those connections to some or all of the neighboring nodes. We say you have just “traversed” one “hop.” Repeat that process to go to the original node’s neighbors’ neighbors, and you have traversed two hops. Since each node can have many connections, this two-hop traversal involves many paths to get from the start nodes to the destination nodes. Graphs are a natural fit for parallel, multithreaded execution.

A query of course should do more than just visit a node. In a simple case, we can count the number of unique two-hop neighbors or make a list of their IDs. How does one compute a total count, when you have multiple parallel counters? The process is similar to what you would do in the real world: Ask each counter to do its share of the world, and then combine their results in the end.

Recall that the query asked for the number of unique nodes. There is a possibility that the same node has been
counted by two different counters, because there is more than one path to reach that destination. This problem can occur even with single-threaded design. The standard solution is to assign a temporary variable to each node. The variables are initialized to False. When one counter visits a node, that node’s variable is set to True, so that other counters know not to count it. The explanation here may sound complex, you can actually write these type of graph traversal with counting and more complex computations in a few lines of code (shorter than this paragraph) using TigerGraph’s high level query language.

**Storage and Processing Engines Written in C++**

Language choices also affect performance. TigerGraph’s graph storage engine and processing engine are implemented in C++. Within the family of general purpose procedural languages, C and C++ are considered lower-level compared to other languages like Java. What this means is that programmers who understand how the computer hardware executes their software commands can make informed choices to optimize performance. TigerGraph has been carefully designed to use memory efficiently and to release unused memory. Careful memory management contributes to TigerGraph’s ability to traverse many links, both in terms of depth and breadth, in a single query.

Many other graph database products are written in Java, which has pros and cons. Java programs run inside a Java Virtual Machine (JVM). The JVM takes care of memory management and garbage collection (freeing up memory that is no longer needed). While this is convenient, it is difficult for the programmer to optimize memory usage or to control when unused memory becomes available.

**GSQL Graph Query Language**

TigerGraph also has its own graph querying and update language, GSQL. While there are many nice details about GSQL, there are two aspects that are key to supporting efficient parallel computation: the ACCUM clause and accumulator variables.

The core of most GSQL queries is the SELECT statement, modeled closely after the SELECT statement in SQL. The SELECT, FROM, and WHERE clauses are used to select and filter a set of links or nodes. After this selection, the optional ACCUM clause may be used to define a set of actions to be performed by each link or adjacent node. I say “perform by” rather than “perform on” because conceptually, each graph object is an independent computation unit. The graph structure is acting like a massively parallel computational mesh. The graph is not just your data storage; it is your query or analytics engine as well.

An ACCUM clause may contain many different actions or statements. These statements can read values from the graph objects, perform local computations, apply conditional statements, and schedule updates of the graph. To support these distributed, in-query computations, the GSQL language provides accumulator variables. Accumulators come in many flavors, but they are all temporary (existing only during query execution), shared (available to any of the execution threads), and mutually exclusive (only one thread can update it at a time). For example, a simple sum accumulator would be used to perform the count of all the neighbors’ neighbors mentioned above. A set accumulator would be used to record the IDs of all those neighbors’ neighbors.
Accumulators are available in two scopes: global and per-node. In the earlier query example, we mentioned the need to mark each node as visited or not. Here, per-node accumulators would be used.

**MPP Computational Model**

To reiterate what we have revealed above, the TigerGraph graph is both a storage model and a computational model. Each node and link can be associated with a compute function. Therefore, each node or link acts as a parallel unit of storage and computation simultaneously. This would be unachievable using a generic NoSQL data store or without the use of accumulators.

**Automatic Partitioning**

In today’s big data world, enterprises need their database solutions to be able to scale out to multiple machines, because their data may grow too large to be stored economically on a single server. TigerGraph is designed to automatically partition the graph data across a cluster of servers, and still perform quickly. The hash index is used to determine not only the within-server data location but also which-server. All the links that connect out from a given node are stored on the same server.

**Distributed Computation Mode**

TigerGraph has a distributed computation mode that significantly improves performance for analytical queries that traverse a large portion of the graph. In distributed query mode, all servers are asked to work on the query; each server’s actual participation is on an as-needed basis. When a traversal path crosses from server A to server B, the minimal amount of information that server B needs to know is passed to it. Since server B already knows about the overall query request, it can easily fit in its contribution.

In a benchmark study, we tested the commonly used PageRank algorithm. This algorithm is a severe test of a graph’s computational and communication speed because it traverses every link, computes a score for every node, and repeats this traverse-and-compute for several iterations. When the graph was distributed across eight servers compared to a single-server, the PageRank query completed nearly seven times faster.

**High Performance Graph Analytics with a Native Parallel Graph**

TigerGraph represents a new era of graph technology that empowers users with true real-time analytics. The technical advantages support more sophisticated, personalized, and accurate analytics, as well as enable organizations to keep up with rapidly changing and expanding data.

As the world’s first and only true native parallel graph (NPG) system, TigerGraph is a complete, distributed, graph analytics platform supporting web-scale data analytics in real time. The TigerGraph NPG is built around both local storage and computation, supports real-time graph updates, and serves as a parallel computation engine. TigerGraph ACID transactions, guaranteeing data consistency and correct results. Its distributed, native parallel graph architecture enables TigerGraph to achieve unequaled performance levels:
• Loading 100 to 200 GB of data per hour, per machine.
• Traversing hundreds of million of nodes/edges per second per machine.
• Performing queries with 10-plus hops in subsecond time.
• Updating 1000s of nodes and edges per second, hundreds of millions per day.
• Scaling out to handle unlimited data, while maintaining real-time speeds and improving loading and querying throughput.

The introduction of native parallel graphs is a milestone in the history of graph databases. Though this technology, the first real-time deep link analytics database has become a reality.
Chapter 6:

Building a Graph Database on a Key-Value Store?

Until recently, graph database designs fulfilled some but not all of the graph analytics needs of enterprises. The first generation of graph databases (e.g., Neo4j) was not designed for big data. They cannot scale out to a distributed database, are not designed for parallelism, and perform slowly at both data loading and querying for large datasets and/or multi-hop queries.

The second generation of graph databases (e.g., DataStax Enterprise Graph) was built on top of NoSQL storage systems such as Apache Cassandra. This addressed the scale-out issue, but since they lack a native graph storage design, they still have slow performance for graph updates or multi-hop queries on large datasets. Faced with the apparent lack of a high-performance graph database solution, some organizations have considered building their own in-house graph solution. Rather than starting from scratch, a modern fast key-value store seems like a good base on which to build a custom graph solution.

The Lure of Key-Value Stores

The NoSQL revolution came about because relational databases were too slow and too inflexible. Big data users needed to ingest a variety of differently structured data, with both high volume and high velocity, and to scale out their physical infrastructure with minimal fuss. The key-value store arose as the simplest and therefore fastest NoSQL architecture. A key-value database is basically a two-column hash table, where each row has a unique key (ID) and a value associated with that key. Searching the key field can return single data values very quickly, much faster than a relational database. Key-value stores also scale well to very large data sets. Key-value stores are well understood, and many free open-source designs are available. It seems fairly straightforward to use a fast key-value store to hold a graph’s node entities and edge entities, implement a little more logic, and call that a graph database.

The Real Cost of Building Your Own Graph Database

Building your own graph database on top of a key-value store, let alone a high-performance one, is much harder than it looks. Here are two obvious difficulties:

1. You are following the architectural principles of the 2nd generation graph databases, but you are trying to improve upon those. Products such as DataStax Enterprise Graph have already optimized performance as
much as they can, given the inherent limitations of a non-native graph storage design.

2. What you really need is a complete database management system (DBMS), not just a graph database. A database is just a collection of data organized in a specific way such that storing and retrieving data are supported. A DBMS, on the other hand, is the complete application program for using and managing data via a database. A DBMS typically includes support for defining a database model, inserting, reading, updating, and deleting data, performing computational queries (not just reading the raw data), applying data integrity checks, supporting transactional guarantees and concurrency, interacting with other applications, and performing administrative functions, such as managing user privileges and security. A do-it-yourself design will need to implement and verify all of these additional requirements.

Let's examine some of the common problems in building a high performance graph on top of key-value storage.

1. Data inconsistency and wrong query results
2. Architectural mismatch with slow performance
3. Expensive and rigid implementation
4. Lack of enterprise support

1. Data Inconsistency and Wrong Query Results

Key value stores are typically highly optimized for high throughput and low latency of single-record reads/writes. As a result, ACID (Atomicity, Consistency, Isolation, Durability) properties are guaranteed only at the single-record level for most key value stores. This means that data consistency is at risk for any real-world transactional events that involve the writing of multiple records (e.g., customer purchases, money transfers, a rideshare request). Lack of data consistency means that queries that aggregate across two or more of these common multi-record transactions can result in incorrect results.

Developers hoping to build a system that businesses can truly trust should realize that data consistency and guaranteeing correct results is an all-or-nothing endeavour. There are no shortcuts for ACID properties. In a graph system, one transaction will often need to create multiple nodes and add new connections/edges between new or existing nodes, all within a single, all-or-nothing transaction. The easy way to guarantee ACID is to perform only one operation at a time, locking out all other operations. But this results in very slow throughput.

In a high-performance design, a transaction must never interfere with, slow down, or block any other existing or incoming read-only queries, even if they are traversing neighboring parts of the graph. If concurrent operations are a business requirement, then developers need to design and engineer a non-blocking graph transactional architecture where multiple key-value transaction support is added inside the distributed key-value system. There are many stories of development teams trying to implement a shortcut workaround that inevitably led to downstream data and query correctness issues.
2. Architectural Mismatch with Slow Performance

Queries involving single records are fast with a key-value store. But key-value store query speeds degrade sharply as queries become more complex. With each hop in the graph traversal, the application has to send a key-value retrieval command to the external key-value store. More hops generate more communication overhead and result in slower query performance. And computation on the data, such as filtering, aggregation, and evidence-gathering, cannot be completely pushed down to the key-value store. Instead, it must take place in the graph application layer, which creates additional input and output transmission with the key-value store while bogging down the query performance even more. Moreover, computing in the graph application layer instead of inside a native parallel graph platform, is by default non-parallel. To match the parallelism in a Native Parallel Graph like TigerGraph, developers would need to take on the extra burden of parallelizing the computation in a single machine or take the even more extraordinary burden of scaling out the computation to multiple machines and taking care of the scheduling, messaging, failover, and other requirements of a distributed system.

Enterprises that want a high-performance graph want a system that analyzes complex relationships and surfaces hidden patterns, with fast query performance. To address these requirements, developers would need to do all of the following: build a graph over key-value application that handles basic graph modeling (describing the structure and behavior of a graph in general), implement basic graph data definition and data manipulation operations, ensure transactional guarantees, and then develop application queries on top of that. That is, in-house developers would need to implement an interpreter for a data definition language (DDL) and a graph query language. Developers should consider the significant time and resources required to support such a challenging endeavor and expect to deal with a lot of unforeseen downstream problem-solving.

3. Expensive and Rigid Implementation

Organizations thinking about creating their own graph database system on top of another database system should consider the resources needed, reliability desired, and ideal adaptability of their application.

Building a graph on key-value system would take a great deal of time to complete. The upfront costs of building custom software should not be underestimated. Furthermore, reliability is critical to application success. As previously discussed, developers should put great thought into how they will design, test, deploy, and support a graph ecosystem that includes full data consistency, correct results, and high performance of complex queries. Finally, management and development teams should consider that a single application likely doesn’t have the general purpose capabilities and flexibility of a high-performance distributed native graph database product. Decision makers should consider the big picture and whether their custom design project can address unforeseen future expansion. By choosing the right graph capabilities now, you can streamline tasks, reduce errors, and make everyone’s life a lot easier for years to come.

4. Lack of Enterprise Support

Last but not least, a custom design will not include many of the features that are crucial for secure and reliable enterprise deployment: user authorization and access control, logging, high availability, and integration with other
applications. Some of these enterprise features might be available for the key-value store, but they need to be available at the graph (application) level.

**Summary**

In summary, designing an application-level graph on top of a key-value store is an expensive and complex job which will not yield a high-performance result. While key-value stores excel at single key-value transactions, they lack ACID properties and the complex transaction functionality required by a graph update. Thus, building a graph database on top of a key value store opens the door to data inconsistencies, wrong query results, slow query performance for multi-hop queries, and an expensive and rigid deployment.

**Example: Updating a Graph**

The following example shows the actions that occur in a typically graph database update. It illustrates how data inconsistency and incorrect results can occur when using a key-value store based graph system and discusses the development challenges and limitations in trying to build functional workarounds.

Consider this update scenario. A real-time event takes place where one user transfers money to another user using a bank card on a mobile phone. Such transactions can be modeled with a simple graph schema, as shown below.

This example applies to many other use cases. For example you can replace the money transfer event with a product purchase event or a service engagement event, such as hiring a ridesharing service.
The money transfer event e1 can be described as the co-occurrence of four entities \((u_1, u_2, c_1, p_1)\), where:

- \(u_1\) is the User sending money,
- \(u_2\) is the User receiving money,
- \(c_1\) is the payment Card used, and
- \(p_1\) is the Phone used.

For simplicity, we ignore all other attributes present in such event (like dollar amount, location, timestamp).

There are multiple ways to model a graph database with a graph over key-value system. One approach is to have two tables in the graph over key-value system: a node table \(V\) and an edge table \(E\). Another approach is to just have a single node table (no edge table) which has a row for each node to store both node attributes and edge information (edge attributes and connected nodes). The transaction challenges faced in either approach are similar and are best illustrated using the two-table approach.

To update the graph by adding a new event e1, we perform the following actions:

1. For each entity \(u_1, u_2, c_1,\) and \(p_1\), check if it already exists. Create a new node for each one that does not yet exist (named \(V_{u_1}, V_{u_2}, V_{c_1}, V_{p_1}\)). Equivalently in the graph over key-value system approach, we need to insert from zero to four rows in the node table \(V\).
2. Create a new node for event e1 (named \(V_{e_1}\) in the following discussion). Equivalently in the graph over key-value system approach, we need to insert one row in the node table \(V\).
3. Add four edges (from \(V_{e_1}\) to each of \(V_{u_1}, V_{u_2}, V_{c_1}\) and \(V_{p_1}\)). To improve query performance, it may be desirable to add an edge between \(V_{u_2}\) and \(V_{c_1}\) and another between \(V_{u_2}\) and \(V_{p_1}\). This will directly connect all cards and phones used by a user but would make a graph over key-value system implementation even more complex and error-prone.

   Also we want to be able to find all events connected to a phone, a user, or a card. This requires adding four additional edges in the other direction: from each of \(V_{u_1}, V_{u_2}, V_{c_1}\), and \(V_{p_1}\) to \(V_{e_1}\). Depending on the implementation detail, this means either adding four rows, or updating the value of four existing rows. The equivalent graph over key-value system approach would need to insert eight rows in the edge table \(E\).
See the following example graph instance:

After the event e1 is processed and the graph is updated, the graph instance would look like the diagram above.

Since the event e1 is treated as a single transaction, the above three actions would happen to the graph (equivalently to two tables) in an atomic way, which means that:

1. Either all three actions are guaranteed to be effective in the graph (or equivalently in two tables), or none of them should be effective in the graph (or equivalently in two tables). A non-transactional system which allows some but not all of the actions to take place (e.g., action 1 and 2 complete successfully but action 3 does not) leads to data inconsistency and wrong results. If any one or more actions do not complete, the result will be missing edges with wrong query results.

2. During the time we apply actions 1, 2 and 3 and before they are completed, their effect should not be visible to any other read or write operations. This means that if you have another query q1, which is still traversing the edges/nodes in the graph before the event e1 comes into the system, q1 should not see any of the actions of 1, 2 and 3 even if they complete successfully before e0 finishes.

3. This also means that if a read-only query q2 comes into the system later than e1 but before the three actions of e1 are all completed, the effects of e1 should not be visible to q.
What are Some Possible Graph Over Key-value Workarounds?

A workaround is to simply ignore all data inconsistency and wrong query result issues and just insert key-value rows to node table V and edge table E and hope for the best. Even if a company’s business requirements can be relaxed to tolerate data inconsistency and wrong query results, this approach is going to face an implementation nightmare. That is because the users don’t know whether or when they will miss a node or edge in the graph. To address this, developers will need to tack on protection code to ensure the application will not hang or crash due to traversing ghost/missing edges.

A better solution would be to add multiple key-value transaction support inside the distributed key-value system. But this requires not only a huge amount of engineering effort but also significant slowdown of key-value operations.

A third solution, a “placebo solution”, is to add some kind of locking mechanism inside the application level without changing the kernel of the underlying key value store. Workarounds, like attempting to add a “commit” flag to each row or maintaining a “dirty” list of rows in their applications, can reduce data inconsistencies and incorrect results. However, such add-on features are not equivalent to an architecture designed for transactional guarantees, so data inconsistencies and incorrect results may persist albeit hidden. Ensuring that these workarounds consistently reconcile and address each transaction can be very difficult to guarantee.
There are many property graph languages on the market, including Neo4j’s Cypher, Apache TinkerPop Gremlin, and TigerGraph’s GSQL, to name a few. Before discussing which graph language is the best, or how to fuse the best aspects of each graph language into a new, unified option, let’s take a step back to ask a more fundamental question: What are the prerequisites for a graph query language in the first place?

Our current era is witnessing a deluge of data — of interconnected data. The power of interconnected data to provide transformative business value is proven by the emergence of giant internet companies, including Google (knowledge graph), Facebook (social graph), LinkedIn (professional network), and Twitter (interest graph). Our communication apps, electronic transactions, smart appliances, and monitoring devices generate enormous volumes of connected data every second. A pressing demand for managing graph data has emerged.

For the first time in the history of databases, the relational model no longer works, because in relational databases
it is too slow to follow a chain of multiple connections. Each hop joins two tables, which is computationally expensive. If you add indexes to the foreign keys, this will speed up the joins, but the general storage and processing model for relational databases is still an impediment..

More importantly, SQL (the query language for relational databases) doesn’t even support a basic discovery operation like “find all records linked by one connection,” because SQL requires that you know in advance what type of entity is being targeted. Simply put, relational databases and the SQL language don’t work for discovery and learning from connected data..

The graph model comes to the rescue by offering these beneficial features:

- Natural and efficient storage model for interconnected data.
- Natural model for managing evolving object types.
- Natural analytical and computational model for knowledge/inference/learning through chaining and combining observations.

The graph database is the answer for managing and leveraging today’s vast and interconnected data. What is the right query language for graphs?

**Eight Prerequisites for a Graph Query Language**

Just as SQL significantly lowered the barrier for managing relational data, a well-designed, user-friendly, and highly expressive graph query language can significantly bridge the gap between asking high-level real world questions and easily crafting a graph-based solution. To pick the right graph query language, let’s look at it from the point of view of the users (developers) and the businesses they work for.

- **Modeling**: How do users want to model their graph data?
- **Querying**: What sort of results do organizations want to obtain from their graphs?
- **Developing**: How easy it is for developers to express their intent in the graph language?

These are all very high level questions, so to answer them we will break them down further. Below we present eight prerequisites for a graph query language for today’s demanding needs.

**1 Schema-Based with Dynamic Schema Change**

A query language actual begins with the data structure it is querying. A strength of the graph model is the ease with which it can reflect the natural organization of data objects. That data organization, or schema, is part of the information. Accordingly, a good graph language should support well-defined schemas, containing user-defined node types and edge types, each with its own set of characteristic properties or attributes. The language should support a wide range of primitive and composite data types. Because data models change over time in the real world, the language and system should also support easy and efficient schema changes, preferably while the
The SQL language is declarative, meaning users ask for data without worrying how the database software executes the queries. This relieves the user from coding a step-by-step algorithm to perform their task. The same paradigm can be applied to designing an elegant graph query language. For example, a simple query to "find this pattern" should be expressed by defining the pattern and defining the search space. It should not have to explain how to conduct the search.

Graphs are capable of much more than simple search, so the query language must support this. Complex analytics and data modifications, where at each hop, computations are performed, data may be updated, and the next action depends on the current state, are possible. For example, consider classical graph algorithms like PageRank, community detection, and centrality measurement, as well as applications like personalized recommendation, fraud detection, supply chain optimization, and predictive analytics. Enterprises come to graph management to design and execute complex algorithms that RDBMS and other NoSQL system cannot solve. Therefore, in addition to declarative semantics, graph query languages also need to provide developers with fine-grained algorithmic control of graph traverse-and-compute. In practice, if the language provides conditional branching ("IF THEN"), looping ("REPEAT"), and variables for temporary data storage, the language is Turing-complete, capable of doing whatever a general purpose computer can do.

Graph algorithms are often expensive, as each hop could increase the data complexity exponentially. Let's consider how: starting from one node, the first hop can yield n neighbors, the next hop from the n immediate neighbors can yield n² more neighbors, and so on. This exponential growth is why many graph databases can't handle more than two hops. To address this challenge, each traversal step in the graph should have built-in parallel processing semantics to ensure high performance. To be sufficiently useful, parallel traversal needs to be combined with a painless means of merging and aggregating.

A full-featured graph query language needs to support more than just efficient graph reads, but also graph writes (data insertions, updates, and deletions). That is, it should support more than just analytics (OLAP) but also transactions (OLTP). A transactional database guarantees that if the user defines a block of operations to be one transaction, then the transaction will complete in its entirety (or not all) and will not interact with any other transactions which might be in process at the same time. The language must provide a way to define a transaction, either implicitly or explicitly, as well as the insert, update, and delete operations.
6 Procedural Queries Calling Queries

As the tasks get more complex, good developers will want to apply one of the best ideas in programming to graph queries: procedural programming. A procedure is a block of instructions that can be saved and "called" when needed. Procedures provide modular design, hierarchical design, abstraction, code reuse, and better readability. For example, consider a query that finds the most influential entity within a radius of K hops from the source node. With procedural querying, this kHopInfluence procedure could be called and reused in multiple larger queries: for recommendation, fraud investigation, optimization, etc. One of the cleverest ideas in algorithm design is recursion, where a procedure calls itself. Depth-first search can be implemented nicely with recursion.

7 SQL User-Friendly

Most enterprises have developers who are familiar with SQL. The graph query language, therefore, should stay close to SQL syntax and concepts as much as possible so that SQL developers can learn and implement graph applications with minimal ramp-up time.

8 Graph-Aware Access Control

Enterprise customers are keen on facilitating collaboration with graph data. On one hand, they want a graph model that can share selected parts of the data among multiple departments and even among partners. At the same time, they also want to keep certain sensitive data private and accessible only by specific roles, departments and partners, based on their business need. Graph schema-aware role-based access control is required for a successful graph query language in the real world for large enterprises.

How Does TigerGraph GSQL Address These Eight Prerequisites?

Based on customer feedback over five years, TigerGraph has co-invented with our customers, over several iterations, a Turing-complete graph query language called GSQL. It includes a DDL (Data Definition Language) for defining a graph schema, a loading language for high-performance loading of structured and semi-structured data, and a SQL-like graph traverse and compute language with inherent parallelism.

Schema-Based with Dynamic Schema Change

In GSQL, a Graph is defined as a collection of Vertex types and Edge types. One TigerGraph database may contain multiple (possibly overlapping) graphs, each with its own set of user privileges and queries. E.g.,

CREATE VERTEX person (PRIMARY_ID ssn STRING, age INT, name STRING)
CREATE UNDIRECTED EDGE friendship (FROM person, TO person)
CREATE DIRECTED EDGE teacher_student (FROM person, TO person)
CREATE GRAPH School (person, friendship, teacher_student)

Also, GSQL's DDL supports dynamic schema change with SQL-like syntax. A schema change job is treated like
other transactions, with the added feature that any queries or loading jobs which become inconsistent with the new schema will be uninstalled.

**High-Level (Declarative) Graph Traversal**

GSQL's building block is a SQL-like SELECT statement to describe a one-hop traversal. To describe a path or a pattern, users can simply include several related SELECT statements in one query. Just as in SQL, the GSQL SELECT statement is high-level and declarative.

**Fine Control of Graph Traversal**

GSQL introduces a set of built-in accumulators, which serve as the nodes' runtime attributes (aka properties). Accumulators can attach to each node traversed, thus users can store tags or intermediate results on nodes during runtime traversal to gather evidence for complex applications such as fraud detection and personalized recommendations. GSQL also has flow control (WHILE and FOREACH loops) and conditional branching (IF-ELSE/CASE-WHEN) to support complex algorithms. Together, these features put the user's hand on the steering wheel. GSQL is Turing-complete, so it can by itself implement any algorithm without the need to exchange data back and forth between the graph database and a client-side application, a practice that can slow down a query by orders of magnitudes.

**Built-in High-Performance Parallel Semantics**

A pair of innovative ACCUM and POST-ACCUM clauses in combination with built-in accumulator variable types encode the parallel processing of a vertex set or edge set, within the same blocks used for high-level graph traversal. This means GSQL enables users to achieve parallel processing of graph data very easily. The ACCUM paradigm enables GSQL users to achieve parallel algorithms without worrying about low-level details. Not every graph query needs this powerful feature, but algorithms from computing a total to PageRank all benefit from GSQL's built-in parallel semantics.

**Transactional Graph Updates**

Each GSQL query, loading job, or REST request is automatically considered a transaction, satisfying ACID properties. The language provides read (SELECT), update, insert, and delete statements, all of which execute in real time. Distributed and concurrent transactions are supported.

**Procedural Queries Calling Queries**

A GSQL query can call a query in several places: in the ACCUM and POST-ACCUM clauses, or at the statement level. This gives the most flexibility and simplicity for solving real-life graph traversal problems. A query can also call itself recursively. This feature enables divide-and-conquer, greatly simplifying query logic and management.

**SQL User-Friendly**

GSQL re-uses much of SQL syntax, semantics, and keywords — SELECT, with FROM, WHERE, HAVING, ORDER BY,
and LIMIT clause, as well as INSERT, UPDATE and DELETE.

Graph-Aware Access Control

MultiGraph, the industry’s first multiple-graph model with role-based access control is an integral part of GSQL, helping TigerGraph’s customers to achieve data sharing and privacy at the same time.
Chapter 8

GSQL — The Modern Graph Query Language

Graph database technology is the fastest growing category in all of data management, according to consultancy DB-Engines.com. A recent Forrester survey shows more than half of global data and analytics technology decision-makers employ graph databases today.

Today, enterprises use graph technology as a competitive edge for customer analytics, fraud detection, risk assessment and other complex data challenges. The technology offers the ability to quickly and efficiently explore, discover, and predict relationships to reveal critical patterns and insights to support business goals.

It’s Time for a Modern Graph Query Language

With the widespread adoption of graph databases, the time is right for a modern graph query language. In the early days of graph databases, several query languages were introduced, such as Neo4j’s Cypher and Apache TinkerPop Gremlin, but these are not without their limitations.

While Cypher is high-level and user-friendly, it is suited primarily for pattern matching rather than analytics, and it must be combined with Java programming to be Turing-complete. There are many graph algorithms and business logic rules that are not possible to implement using Cypher. An example is a PageRank/Label Propagation style algorithm, where variances are important for verticals such as power flow computation and optimization, risk analytics and more.

Gremlin is Turing-complete but low level. The language works well for very simple queries, but when it comes to real-life business problems, advanced programming skills are needed, and the resulting query can be hard to understand and maintain. A technical comparison of graph query languages presented in the next chapter.

As data and use cases grow and become more complex, it’s clear organizations need both the ability to scale out and the ability to perform complex analytics for tasks such as machine learning and AI, and with the speed for real-time operations.

A modern and standardized language will also help solve pervasive challenges in the graph market, which include the difficulty of finding proficient graph developers and the need to speed up enterprise adoption. Lowering the

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2 [https://www.forrester.com/report/Vendor+Landscape+Graph+Databases/-/E-RES121473](https://www.forrester.com/report/Vendor+Landscape+Graph+Databases/-/E-RES121473)
barrier to learning and implementing graph applications — via a High Level Graph Query Language — makes it easier for more developers to bridge the gap between asking high-level real-life questions and easily crafting a graph-based solution.

A modern graph query language, along with a super-fast and scalable system to support it, is also key to helping enterprises achieve digital transformation at scale.

**What Should a Modern Graph Query Language Look Like?**

Let’s take a step back and understand why users are choosing graph databases over RDBMS, key-value, document store and other types of databases. Typically it is because they want to solve complex problems with satisfying performance. Non-graph databases have shortcomings such as the following:

- Extreme difficulty expressing real-world business problems. For example, how are entities such as accounts or people connected in various (and often previously unknown) ways, especially to known bad actors?
- Dismal real-time performance when accessing 10s to 100s millions of entities and their relationships. Speed is of the essence when it comes to applications such as real-time personalized recommendations, fraud detection, and more.

A graph database provides the platform for solving these problems, but users still need the appropriate query language: to define graph schemas to model complex entities and relationships, to easily map all kinds of data sources to a graph, to load data to a graph quickly, and to be expressive enough (Turing-complete) to model and solve real-life business problems in all kinds of industries. These are key to enabling graph technology to cross the chasm for more widespread enterprise adoption.

Given this, experts have called out eight key characteristics important to a modern, graph query language:
1) schema-based with dynamic schema change, 2) high-level (declarative) graph traversal, 3) fine control of graph traversal, 4) built-in parallel semantics to guarantee high performance, 5) transactional graph updates, 6) procedural queries calling queries (recursively), 7) SQL user-friendly, and 8) graph-aware access control.

**Introducing GSQL**

GSQL is a user-friendly, highly expressive, and Turing-complete graph query language. Unlike other options, GSQL supports the real-life business requirements organizations already experience and is designed from the ground up to meet the criteria above.

In fact, development of GSQL was sparked after an unsuccessful search for a modern graph query language that could adequately address real business needs. When TigerGraph was founded six years ago, we decided to put in the time (several years) to create GSQL to alleviate this pain point. We engineered it from square one to support
parallel loading, querying, and updates for real-time transactions and ultra-fast analytics.

With GSQL, customers gain data insights they previously thought were unobtainable. In other words, GSQL has enabled them to make the impossible possible. GSQL is in use by some of the largest companies and supports the world’s largest graph deployment with over two billion real-time transactions per day.

Users also report GSQL’s ease of use for creating queries over big data. Speed has been another benefit, as GSQL queries deliver results in seconds, compared to hours using solutions such as Cypher or Gremlin — that is, if the query is even possible at all. In short, GSQL satisfies what matters most in a graph query language: performance, expressiveness, and ease-of-use.

The Conceptual Descendent of MapReduce, Gremlin, Cypher, SPARQL and SQL

GSQL was not developed in a vacuum. It embodies many of the best ideas from its graph query language antecedents and from SQL, of course. Because of this, GSQL typically can support the functionality of any its predecessors, and there is often a straightforward mapping of the syntax from earlier languages to GSQL.

As the relational database become the dominant database paradigm starting in the 1970s and into the 1980s, SQL emerged as the standard query language. It is SQL was based on a strict logical model: relational algebra. Correctness and declarative syntax were paramount, not performance. SPARQL is for querying RDF data; version 1.0 became a W3C recommendation in January 2008. Gremlin, Cypher, and GSQL are all targeted at property graphs. Gremlin first appeared in October 2009 as an Apache TinkerPop project. Cypher was introduced by Neo4j in 2011, and GSQL was developed by TigerGraph in 2014.

When GSQL was designed, it was driven primarily by customers’ real-world needs. None of the other graph query languages (e.g., Cypher, Gremlin) could satisfy the needs of the early TigerGraph adopters. GSQL took shape as a careful balance between serving the needs of users performing complex analytics and the preserving as much similarity to SQL and other common programming languages as possible. Since GSQL emerged after the other languages mentioned had their initial releases, it had the advantage of hindsight to inherit their best features and to avoid their pitfalls. We elaborate on each below.

SQL Inheritance

From the beginning, GSQL has used the bulk synchronous parallel (BSP) model to parallelize its graph query processing. Needing a way to describe one iteration or one hop in the graph, we chose to use the SQL SELECT-FROM-WHERE block structure as that basic building block, and use other keywords, such as HAVING, ORDER BY, LIMIT, INSERT, and others as much as possible. Also, GSQL has DDL statements, to declare vertex (node), edge, and graph types, such as CREATE VERTEX person(primary_id name string, age int). The syntax is very similar to SQL’s CREATE TABLE. Cypher also inherits some SQL keywords (though not SELECT, the most common statement type in SQL), so GSQL is indirectly similar to Cypher.
Map-Reduce Inheritance

Secondly, GSQL introduced the ACCUM and POST-ACCUM clauses to support Map-Reduce semantics natively in the SELECT block. The ACCUM clause acts as the Map step; it parallel processes all the matched edges. The POST-ACCUM clause acts as the Reduce step; it merge-processes the source or target node’s messages emitted from the ACCUM clause.

Gremlin Runtime Variable

Gremlin is a functional chain-style query language. It has a traversal instruction set, and a set of traversers. The query results are the halted traversers’ locations. A key concept in Gremlin is the side effect (anything that happens in addition to the traversal itself, including runtime variables). There are global side effects and local side effects. A local side effect is implemented as sack(). Each traverser can maintain a local data structure called sack, and it can use sack-step to read or write the sack variable. A global side effect withSideEffect() can be used to hold a global variable. The entire query’s side effects are associated with a traverser, so the data structure can get very complex and convoluted (corresponding to the runtime traversal tree).

GSQL has a similar concept, however, the conceptual complexity is much lower. In GSQL, a user can define any number of local accumulators (having names starting with @) or global accumulators (having names starting with @@). Syntax is very straightforward. To read an accumulator, treat it like a vertex attribute (e.g., v.@sum). To write, use the accumulate operator +=. Unlike Gremlin, local accumulators are not tied to each traverser but to each visited node. Global accumulators are accessible anywhere in the query body.

SPARQL Triple Pattern Match

GSQL describes a 1-hop traversal as the set of edges matching a triple in the FROM clause:

```
source_vertex_set -(edge_types)-> target_vertex_types
```

This triple is almost identical to SPARQL’s triple pattern match style. However, GSQL does not put the pattern in the WHERE clause, as SPARQL does. GSQL put patterns in the FROM clause to distinguish them as first class citizens.

Cypher match patterns as first class citizens - a vertex pattern, an edge pattern, or a path pattern is the main characteristic of Cypher. Similarly, in GSQL, edge patterns and vertex patterns are the first class citizens, in the FROM clause. GSQL will be adding support for path patterns in the near future.

Putting It All Together

GSQL inherits and borrows many useful features from prior graph query languages and from SQL. The art is in knowing what to adopt and what to discard. More significantly, GSQL added flow control to support high level iteration (WHILE, FOREACH) and conditionals (IF...ELSE, CASE), giving users the syntax vocabulary they are most familiar with, to achieve Turing completeness.
Also, a GSQL query can contain any number of SELECT blocks (single hops). The data flow does not have to form a contiguous chain. Each SELECT block can start from a new or a previously visited part of the graph, as long as each FROM clause’s starting vertices are defined. In general, the hops form a DAG (directed acyclic graph).

This one-hop-at-a-time approach, with Map-Reduce aggregation and accumulators — vertex-attached and global — available in each step, and with the ability to combine hops in almost any way, enablers users to break down their code into easy to manage pieces, and then combine them to make amazingly powerful algorithms. Overly, a GSQL query language is analogous to Oracle PL/SQL or Microsoft SQL Server stored procedure syntax.

**GSQL 101 - A Tutorial**

To get a flavor for the simplicity and power of GSQL, the remaining of this chapter presents a tutorial which walks you through defining a graph schema, loading data, and using simple built-in queries. The next chapter will introduce queries for more complex tasks and compare the capabilities of GSQL to those of other graph query languages.

*Note: The GSQL language uses the keyword vertex to refer to a graph node.*

**Data Set**

For this example, we will create and query the simple friendship social graph shown in Figure 1. The data for this graph consists of two files in csv (comma-separated values) format. To follow along with this tutorial, please save these two files, person.csv and friendship.csv, to your TigerGraph local disk. In our running example, we use the /home/tigergraph/ folder to store the two csv files.
person.csv

<table>
<thead>
<tr>
<th>name</th>
<th>gender</th>
<th>age</th>
<th>state</th>
</tr>
</thead>
<tbody>
<tr>
<td>Tom</td>
<td>male</td>
<td>40</td>
<td>ca</td>
</tr>
<tr>
<td>Dan</td>
<td>male</td>
<td>34</td>
<td>ny</td>
</tr>
<tr>
<td>Jenny</td>
<td>female</td>
<td>25</td>
<td>tx</td>
</tr>
<tr>
<td>Kevin</td>
<td>male</td>
<td>28</td>
<td>az</td>
</tr>
<tr>
<td>Amily</td>
<td>female</td>
<td>22</td>
<td>ca</td>
</tr>
<tr>
<td>Nancy</td>
<td>female</td>
<td>20</td>
<td>ky</td>
</tr>
<tr>
<td>Jack</td>
<td>male</td>
<td>26</td>
<td>fl</td>
</tr>
</tbody>
</table>

friendship.csv

<table>
<thead>
<tr>
<th>person1</th>
<th>person2</th>
<th>date</th>
</tr>
</thead>
<tbody>
<tr>
<td>Tom</td>
<td>Dan</td>
<td>2017-06-03</td>
</tr>
<tr>
<td>Tom</td>
<td>Jenny</td>
<td>2015-01-01</td>
</tr>
<tr>
<td>Dan</td>
<td>Jenny</td>
<td>2016-08-03</td>
</tr>
<tr>
<td>Jenny</td>
<td>Amily</td>
<td>2015-06-08</td>
</tr>
<tr>
<td>Dan</td>
<td>Nancy</td>
<td>2016-01-03</td>
</tr>
<tr>
<td>Nancy</td>
<td>Jack</td>
<td>2017-03-02</td>
</tr>
<tr>
<td>Dan</td>
<td>Kevin</td>
<td>2015-12-30</td>
</tr>
</tbody>
</table>

Prepare Your TigerGraph Environment

First, let's check that you can access GSQL.

1. Open a Linux shell.
2. Type `gsql` as below. A GSQL shell prompt should appear as below.
3. Linux shell
4. `$ gsql
   GSQL >
5. If the GSQL shell does not launch, try resetting the system with "gadmin restart all". If you need further help, please see the TigerGraph Knowledge Base and FAQs.

If you need to reset everything, the command DROP ALL will delete all the database data, its schema, and all related definitions. This command takes about a minute to run.

---

3 We have omitted some of the administrative commands and steps that you might need to address if you are running this on a real system. For the full instructions, see https://doc.tigergraph.com/GSQL-101.html
**GSQL shell - DROP ALL**

```
GSQL > drop all
Dropping all, about 1 minute ...
Abort all active loading jobs
[ABORT_SUCCESS] No active Loading Job to abort.
Shutdown restpp gse gpe ...
Graph store /usr/local/tigergraph/gstore/0/ has been cleared!
Everything is dropped.
```

**Tip: Running GSQL commands from Linux**

You can also run GSQL commands from a Linux shell. To run a single command, just use “gsql” followed by the command line enclosed in single quotes. (The quotes aren’t necessary if there is no parsing ambiguity; it’s safer to just use them.) For example,

```
# “-g graphname” is need for a given graph
gsql -g social 'ls'
gsql 'drop all'
gsql 'ls'
```

You can also execute a series of commands which you have stored in a file, by simply invoking “gsql” following by the name of the file.

When you are done, you can exit the GSQL shell with the command “quit” (without the quotes).

**Define a Schema**

For this tutorial, we will work mostly in the GSQL shell, in interactive mode. A few commands will be from a Linux shell. The first step in creating a GSQL graph is to define its schema. GSQL provides a set of DDL (Data Definition Language) commands, similar to SQL DLL commands, to model vertex types, edge types and a graph.

**Create a Vertex Type**

Use CREATE VERTEX command to define a vertex type named `person`. Here, PRIMARY_ID is required: each person must have a unique identifier. The rest is the optional list of attributes which characterize each person vertex, in the format `attribute_name data_type, attribute_name data_type, ..`

**GSQL command**

```
CREATE VERTEX person (PRIMARY_ID name STRING, name STRING, age INT, gender STRING, state STRING)
```
We show GSQL keywords in ALL CAPS to highlight them, but in fact they are case-insensitive.

GSQL will confirm the creation of the vertex type.

**GSQL shell**

```gsql
GSQL > CREATE VERTEX person (PRIMARY_ID name STRING, name STRING, age INT, gender STRING, state STRING)
The vertex type person is created.
GSQL >
```

You can create as many vertex types as you need.

**Create an Edge Type**

Next, use the CREATE ... EDGE command to create an edge type named `friendship`. The keyword UNDIRECTED indicates this edge is a bidirectional edge, meaning that information can flow starting from either vertex. If you'd rather have a unidirectional connection where information flows only from the FROM vertex, use the DIRECTED keyword in place of UNDIRECTED. Here, FROM and TO are required to specify which two vertex types the edge type connects. An individual edge is specifying by giving the primary_ids of its source (FROM) vertex and target (TO) vertex. These are followed by an optional list of attributes, just as in the vertex definition.

**GSQL command**

```gsql
CREATE UNDIRECTED EDGE friendship (FROM person, TO person, connect_day DATETIME)
```

GSQL will confirm the creation of the edge type.

**GSQL shell**

```gsql
GSQL > CREATE UNDIRECTED EDGE friendship (FROM person, TO person, connect_day DATETIME)
The edge type friendship is created.
GSQL >
```

You can create as many edge types as you need.

**Create a Graph**

Next, use the CREATE GRAPH command to create a graph named `social`. Here, we just list the vertex types and edge types that we want to include in this graph.

**GSQL command**

```gsql
```
CREATE GRAPH social (person, friendship)

GSQL will confirm the creation of the first graph after several seconds, during which it pushes the catalog information to all services, such as the GSE, GPE and RESTPP.

**GSQL shell**

```
GSQL > CREATE GRAPH social (person, friendship)

Restarting gse gpe restpp ...
Finish restarting services in 16.554 seconds!
The graph social is created.
```

At this point, we have created a **person** vertex type, a **friendship** edge type, and a **social** graph that includes them. You've now built your first graph schema! Let's take a look what's in the catalog by typing the “ls” command in the GSQL shell.

**GSQL shell**

```
GSQL > ls
---- Global vertices, edges, and all graphs
Vertex Types:
  - VERTEX person(PRIMARY_ID name STRING, name STRING, age INT, gender STRING, state STRING) WITH STATS="OUTDEGREE_BY_EDGETYPE"
Edge Types:
  - UNDIRECTED EDGE friendship(FROM person, TO person, connect_day DATETIME)
Graphs:
  - Graph social(person:v, friendship:e)
Jobs:

Json API version: v2
```

**Load Data**

After creating a graph schema, the next step is to load data into it. The task here is to instruct the GSQL loader how to associate (“map”) the fields in a set of data files to the attributes in your vertex types and edge types of the graph schema we just defined.

You should have the two data files person.csv and friendship.csv on your local disk. It’s not necessary that they are in the same folder with you.
If you need to exit the GSQL shell for any reason, you can do so by typing "quit" without the quotes. Type gsql to enter again.

Define a Loading Job

The loading job below assumes that your data files are in the folder /home/tigergraph. If they are elsewhere, then in the loading job script below replace "/home/tigergraph/person.csv" and "/home/tigergraph/friendship.csv" with their corresponding file path respectively. Assuming you’re (back) in the GSQL shell, enter the following set of commands.

GSQl commands to define a loading job

```
USE GRAPH social
BEGIN
CREATE LOADING JOB load_social FOR GRAPH social {
    DEFINE FILENAME file1="/home/tigergraph/person.csv";
    DEFINE FILENAME file2="/home/tigergraph/friendship.csv";
    LOAD file1 TO VERTEX person VALUES ($"name", "$name", "$age", "$gender",
    "$state") USING header="true", separator="",
    LOAD file2 TO EDGE friendship VALUES ($0, $1, $2) USING header="true",
    separator="",
}
END
```

Let’s walk through the commands:

- **USE GRAPH social:**
  Tells GSQL which graph you want to work with.

- **BEGIN ... END:**
  Indicates multiple-line mode. The GSQL shell will treat everything between these markers as a single statement. These is only needed for interactive mode. If you run GSQL statements that are stored in a command file, the command interpreter will study your whole file, so it doesn’t need the BEGIN and END hints.

- **CREATE LOADING JOB:**
  One loading job can describe the mappings from multiple files to multiple graph objects. Each file must be assigned to a filename variable. The field labels can be either by name or by position. By-name labelling requires a header line in the source file. By-position labelling uses integers to indicate source column position 0, 1, ... In the example above, the first LOAD statement refers to the source file columns by name, whereas the second LOAD statement refers to the source file columns by position. Note the following details:
• The column "name" in file1 gets mapped to two fields, both the PRIMARY_ID and the "name" attribute of the person vertex.

• In file1, gender comes before age. In the person vertex, gender comes after age. When loading, state your attributes in the order needed by the target object (in this case, the person vertex).

• Each LOAD statement has a USING clause. Here it tells GSQL that both files contain a header (whether we choose to use the names or not, GSQL still needs to know whether to consider the first line as data or not). It also says the column separator is comma. GSQL can handle any single-character separator, not just commas.

When you run the CREATE LOADING JOB statement, GSQL checks for syntax errors and checks that you have data files in the locations specified. If it detects no errors, it compiles and saves your job.

GSQL shell

```
GSQL > USE GRAPH social
Using graph 'social'
GSQL > BEGIN
GSQL > CREATE LOADING JOB load_social FOR GRAPH social {
GSQL >    DEFINE FILENAME file1="/home/tigergraph/person.csv";
GSQL >    DEFINE FILENAME file2="/home/tigergraph/friendship.csv";
GSQL >    LOAD file1 TO VERTEX person VALUES ($"name", "$name", "$age", "$gender", "$state") USING header="true", separator="","
GSQL >    LOAD file2 TO EDGE friendship VALUES ($0, $1, $2) USING header="true", separator="","
GSQL > }
GSQL > END
The job load_social is created.
```

Run a Loading Job

You can now run your loading job to load data into your graph:

**GSQL command**

```
RUN LOADING JOB load_social
```

The result is shown below.

**GSQL shell**

```
GSQL > run loading job load_social
```
Starting the following job, i.e.

- **JobName**: load_social, **jobid**: social_m1.1528095850854
- **Loading log**: '/home/tigergraph/tigergraph/logs/restpp/restpp_loader_logs/social/social_m1.1528095850854.log'

Job “social_m1.1528095850854” loading status

[FINISHED] m1 (Finished: 2 / Total: 2)

<table>
<thead>
<tr>
<th>FILENAME</th>
<th>LOADED LINES</th>
<th>AVG SPEED</th>
<th>DURATION</th>
</tr>
</thead>
<tbody>
<tr>
<td>/home/tigergraph/friendship.csv</td>
<td>8</td>
<td>8 l/s</td>
<td>1.00 s</td>
</tr>
<tr>
<td>/home/tigergraph/person.csv</td>
<td>8</td>
<td>7 l/s</td>
<td>1.00 s</td>
</tr>
</tbody>
</table>

Notice the location of the loading log file. The example assumes that you installed TigerGraph in the default location, /home/tigergraph/. In your installation folder is the main product folder, tigergraph. Within the tigergraph folder are several subfolders, such as logs, document, config, bin, and gstore. If you installed in a different location, say /usr/local/, then you would find the product folder at /usr/local/tigergraph.

**Query Using Built-In SELECT Queries**

You now have a graph with data! You can run some simple built-in queries to inspect the data.

**Select Vertices**

The following GSQL command reports the total number of person vertices. The person.csv data file had 7 lines after the header.

**GSQL command**

```
SELECT count() FROM person
```

Similarly, the following GSQL command reports the total number of friendship edges. The friendship.csv file also had 7 lines after the header.

**GSQL command**

```
SELECT count() FROM person-(friendship)->person
```
The results are illustrated below.

**GSQL shell**

```
GSQL > SELECT count() FROM person
[{
   "count": 7,
   "v_type": "person"
}]
GSQL > SELECT count() FROM person-(friendship)->person
[{
   "count": 14,
   "e_type": "friendship"
}]
GSQL >
```

**Edge Count**

Why are there 14 edges? For an undirected edge, GSQL actually creates two edges, one in each direction.

If you want to see the details about a particular set of vertices, you can use "SELECT *" and the WHERE clause to specify a predicate condition. Here are some statements to try:

**GSQL command**

```
SELECT * FROM person WHERE primary_id=="Tom"
SELECT name FROM person WHERE state=="ca"
SELECT name, age FROM person WHERE age > 30
```

The result is in JSON format as shown below.

**GSQL shell**

```
GSQL > SELECT * FROM person WHERE primary_id=="Tom"
[{
   "v_id": "Tom",
   "attributes": {
      "gender": "male",
      "name": "Tom",
      "state": "ca",
      "age": 40
   }
},
```
GSQL > SELECT name FROM person WHERE state=="ca"

[ 
  { 
    "v_id": "Amily",
    "attributes": { "name": "Amily" },
    "v_type": "person"
  },
  { 
    "v_id": "Tom",
    "attributes": { "name": "Tom" },
    "v_type": "person"
  }
]

GSQL > SELECT name, age FROM person WHERE age > 30

[ 
  { 
    "v_id": "Tom",
    "attributes": { 
      "name": "Tom",
      "age": 40
    },
    "v_type": "person"
  },
  { 
    "v_id": "Dan",
    "attributes": { 
      "name": "Dan",
      "age": 34
    },
    "v_type": "person"
  }
]
Select Edges

In similar fashion, we can see details about edges. To describe an edge, you name the types of vertices and edges in the three parts, with some added punctuation to represent the traversal direction:

**GSQL syntax**

```
source_type -(edge_type)-> target_type
```

Note that the arrow -> is always used, whether it's an undirected or directed edge. That is because we are describing the direction of the query’s traversal (search) through the graph, not the direction of the edge itself.

We can use the from_id predicate in the WHERE clause to select all friendship edges starting from the vertex identified by the “from_id”. The keyword ANY to indicate that any edge type or any target vertex type is allowed. The following two queries have the same result:

**GSQL command**

```
SELECT * FROM person-(friendship)->person WHERE from_id =="Tom"
SELECT * FROM person-(ANY)->ANY WHERE from_id =="Tom"
```

**Restrictions on built-in edge select queries**

To prevent queries which might return an excessive number of output items, built-in edge queries have the following restrictions:

1. The source vertex type must be specified.
2. The from_id condition must be specified.

There is no such restriction for user-defined queries.

The result is shown below.
Another way to check the graph’s size is using one of the options of the administrator tool, gadmin. From a Linux shell, enter the command

gadmin status graph -v

**Linux shell**

[tigergraph@localhost ~]$ gadmin status graph -v
verbose is ON
=== graph ===
[m1 ] [GRAPH] [MSG ] Graph was loaded (/usr/local/tigergraph/gstore/0/part/): partition size is 4.00KiB, SchemaVersion: 0, VertexCount: 7, NumOfSkippedVertices: 0, NumOfDeletedVertices: 0, EdgeCount: 14
[m1 ] [GRAPH] [INIT] True
[INFO ] [GRAPH] [MSG ] Above vertex and edge counts are for internal use which show approximate topology size of the local graph partition. Use DML to get the correct graph topology information
[SUMMARY][GRAPH] graph is ready
In the previous chapter, we presented the main reasons why GSQL is the modern graph query language, especially for real-time deep link analytics. We also walked through a beginning tutorial, to give you some first hand familiarity with GSQL.

In this chapter, we look at some realistic queries as examples for analyzing the technical capacities of GSQL. When then examine three other graph query languages, Gremlin, Cypher, and SPARQL, to see how they compare.

Note: Both GSQL and Gremlin languages use the keyword vertex to refer to a graph node, therefore in the chapter we say vertex instead of node, even when speaking more abstractly.

Example 1: Business Analytics - Basic

Suppose we are in interesting in finding, for each customer c, the total revenue earned from sales of products in the “toy” category to c. Our schema has Customer and Product vertices and Bought edges. Each Product has a price, and each purchase has a quantity and a discount.

\[
\text{SumAccum<float> @revenue;}
\]
It is easy to see that line (6) computes how much revenue is generated from a purchase (Bought edge) b of Product p for Customer c. What is less obvious is that the ACCUM clause and the SumAccum accumulator "@revenue" (line 1) automatically take care of iterating (in parallel) over all Bought edges for customers who bought a "toy", that each customer has its own runtime "@revenue", and though multiple processes might be adding to the same accumulator at the same time, the accumulators automatically ensure there is no conflict. The parallel processing paradigm should be familiar to developers who have worked with MapReduce.

Example 2: Graph Algorithms

PageRank can easily be implemented in GSQL. PageRank, which computes the relative authority of nodes, is essential for many applications where finding important or influential entities is needed (targeted marketing, impact prediction, optimal use of limited resources, etc). Other graph algorithms, such as community detection and shortest path discovery, similarly have many real-world applications. Being able to implement and customize graph algorithms purely in a high-level graph query language is critical for such use cases. Conversely, a hard-coded PageRank algorithm does not provide users with the expressive power to solve real-life problems.

GSQL queries can be treated as parameterized procedures, as seen in the initial CREATE QUERY statement below in Example 2. (We omitted the CREATE statement in Example 1 to keep it simple.)
\[ s.@recvd\textunderscore score = 0, \]
\[ @@maxDiff += \text{abs}(s.@score - s.@score'); \]

END; #end while loop

PRINT V;
}#end query

**Advanced Accumulation and Data Structures**

So far, we have shown accumulators that aggregate numeric data into a single scalar result value. The expressive power of GSQL is significantly enhanced by its support for complex-valued accumulators, which contain for instance collections of tuples, possibly partitioned into groups, and optionally aggregated per group.

**Example 3**

We refine the revenue aggregation to show, for each customer \( c \), the revenue by product category and the revenue by discount.

\[
\text{GroupByAccum<}\text{string categ}, \text{SumAccum<float> revenue}\> @byCateg; \quad #1
\]
\[
\text{GroupByAccum<int disc, SumAccum<float> revenue}> @byDiscount; \quad #2
\]
\[
\text{Start} = \{\text{Customer.}\ast\}\}; \quad #3
\]
\[
\text{Cust} = \text{SELECT } c \quad #4
\]
\[
\text{FROM Start:c -(Bought:b)-> Product:p} \quad #5
\]
\[
\text{ACCUM } c.@byCateg += (p.category->p.price*(1-b.discount/100.0)*b.quantity), \quad #6
\]
\[
c.@byDiscount += (b.discount->p.price*(1-b.discount/100.0)*b.quantity); \quad #7
\]

Notice the declaration (in Line 1) of vertex accumulators called ‘byCategory’. These are group-by accumulators that define the string attribute ‘categ’ as the group key and that associate to each group a sum accumulator called ‘revenue’, which is in charge of aggregating the group’s values.

Line (6) shows the syntax for writing the value \( p.price*(1-b.discount/100.0)*b.quantity \) into the ‘revenue’ sum accumulator corresponding to the group of key \( p.category \) in the byCateg accumulator located at vertex \( c \). A similar group-by accumulator is defined in Line 2 to group sales by discount value, summing up the sales in each group. To support the manipulation of accumulator values of collection type, GSQL also includes a foreach primitive that iterates over the elements of the collection, binding a variable to them.
Multi-hop Traversals with Intermediate Result Flow

GSQL supports the specification of analytics that involve traversing multi-hop paths in the graph while propagating intermediate results computed along the way. The following example illustrates how one can concisely express a simple recommender system in GSQL.

Example 4

The following GSQL query generates a list of toy recommendations for customer 1. The recommendations are ranked in the classical manner of recommender systems: each recommended toy’s rank is a weighted sum of the likes by other customers. Each like by customer c is weighted by the similarity of c to customer 1. This similarity is the standard log-cosine similarity, which reflects how many toys customers 1 and c already like in common. More formally, for each customer c we define a vector \( \text{likes}_c \) of bits, such that bit i is set if and only if customer c likes toy i. The log-cosine similarity measure between two customers x and y is defined as

\[
lc(x, y) = \log(1 + \text{likes}_x \cdot \text{likes}_y)
\]

where \( \cdot \) denotes the dot product of two vectors. Note that \( \text{likes}_x \cdot \text{likes}_y \) simply counts the number of toys liked in common by customers x and y. In the following, we assume that the fact that customer c likes product p is modeled as a unique edge connecting c to p, labeled Likes.

```sql
SumAccum<float> @rank, @lc;                                             #1
SumAccum<int> @inCommon;                                               #2
Start = {Customer.1};                                                   #3
ToysILike =                                                                #4
   SELECT p                                                             #5
   FROM Start:c -(Likes)-> Product:p                                      #6
   WHERE p.category == "toy";                                             #7
OthersWhoLikeThem =                                                        #8
   SELECT o                                                               #9
   FROM ToysILike:t -(Likes)-> Customer:o                                #10
   WHERE o.id != 1                                                       #11
   ACCUM o.@inCommon += 1                                                #12
   POST-ACCUM o.@lc = log (1 + o.@inCommon);                             #13
ToysTheyLike =                                                            #14
   SELECT t                                                              #15
   FROM OthersWhoLikeThem:o -(Likes)-> Product:t                         #16
   WHERE t.category == "toy"                                             #17
   ACCUM t.@rank += o.@lc;                                               #18
RecommendedToys = ToysTheyLike MINUS ToysILike;                           #19
```
The query specifies a traversal that starts from customer 1, then in a first block follows Likes edges to the toys she likes (Line 6), storing them in the ToysILike vertex set (Line 4). In the second block, the traversal continues from these toys, following inverse Likes edges to the other customers who also like some of these toys (Line 10). These customers are stored in the vertex set OthersWhoLikeThem. The third block continues from these customers, following Likes edges to toys they like (Line 16), storing these in the vertex set ToysTheyLike. Notice how blocks are chained together by using the output vertex set of a block as the input vertex set of the successor block. The recommended toys are obtained as the difference of the ToysTheyLike and the ToysILike vertex sets, as we do not wish to recommend toys customer 1 already likes.

Along the traversal, the following aggregations are computed. The second block counts how many toys each other customer o likes in common with customer 1, by writing the value 1 into o's vertex accumulator o.@inCommon for every toy liked by o (Line 12). These unit values are aggregated into a sum by the vertex accumulator, whose final value represents the desired count. In the post-accumulation phase, when the count value is final, Line 13 computes the log-cosine similarity of customer o with customer 1. The third block now writes to each toy t the similarity value o.@lc of every customer o who likes t (Line 18). At the end of the accumulation phase, t.@rank contains the sum of these values, which is precisely the definition of the rank.

Note how intermediate results computed in a block are accessible to subsequent blocks via the accumulators (e.g., customer o's log-cosine similarity to customer 1 is stored by the second block into the vertex accumulator @lc, which is read by the third block to compute the toy's rank).

**Control Flow**

GSQL's global control flow primitives comprise if-then-else style branching (including also the standard case switches borrowed from SQL), as well as while loops, both guarded by boolean conditions involving global accumulators, global variables, and query parameters. This is particularly useful for expressing iterative computation in which each iteration updates a global intermediate result used by the loop control to decide whether to break out of the loop. A prominent example is the PageRank algorithm variant that iterates until either a maximum iteration number is reached or the maximum error in rank computation over all vertices (aggregated in a global Max accumulator) is lower than a given threshold (provided for instance as parameter to the query).

Loops can be arbitrarily nested within each other, with the code of the innermost loop being a directed acyclic graph of blocks (the looping of course permits cyclic data flow through the graph).
Query Calling Query

GSQL supports queries calling named, parameterized queries. GSQL supports vertex-, edge- as well as attribute-level modifications (insertions, deletions and updates), with a syntax inspired by SQL.

Turing Completeness

As previously stated, GSQL is Turing-complete. This is clear when you observe GSQL’s support for conditional branching, looping, and storage variables.

GSQL Compared to Other Graph Languages

GSQL can be compared to other prominent graph query languages in circulation today. This comparison seeks to transcend the particular syntax or the particular way in which semantics are defined, focusing on expressive power classified along the following key dimensions.

1. **Accumulation**: What is the language support for the storage of (collected or aggregated) data computed by the query?
2. **Multi-hop Path Traversal**: Does the language support the chaining of multiple traversal steps into paths, with data collected along these steps?
3. **Intermediate Result Flow**: Does the language support the flow of intermediate results along the steps of the traversal?
4. **Control Flow**: What control flow primitives are supported?
5. **Query-Calling-Query**: What is the support for queries invoking other queries?
6. **SQL Completeness**: Is the language SQL-complete? That is, is it the case that for a graph-based representation G of any relational database D, any SQL query over D can be expressed by a GSQL query over G?
7. **Turing completeness**: Is the language Turing-complete?

Gremlin

Gremlin is a graph query language that specifies graph analytics as pipelines of operations through which objects (called “traversers”) flow, evolving and collecting information along the way. Operations can for instance replace (within the traverser) a vertex with its in- or out-neighbor, its in- or out-edge, its attribute, etc., while also extending the traverser with bindings of variables to values computed from the contents of the traverser. The semantics of Gremlin is specified operationally, in functional programming style.
Gremlin is a Turing-complete language and as such as expressive as GSQL. We detail below how it covers the expressivity dimensions we articulated, referring to the Apache TinkerPop3 v3.2.7 documentation.

1. Accumulation
   Gremlin supports the collection of data (into lists or tables), as well as their aggregation using either user-defined aggregation functions or the usual SQL built-in aggregates. Group-by aggregation is supported as in SQL, by defining a relational table, specifying its grouping attributes and aggregated columns.
   
   • Gremlin inherits a limitation from SQL: like SQL queries, Gremlin queries can group a table by one group-by attribute list or by another, but not simultaneously by both. Achieving two different group-by aggregations of the same collected data would require a verbose query that defines the same table of variable bindings twice, grouping each table accordingly. Contrast this with the ease with which GSQL specifies the simultaneous computation of the two groupings of the same data by simply writing each value into two distinct grouping accumulators.
   
   • Intermediate results computed during the traversal can be stored either in global variables via the “sideeffect” operator (akin to GSQL's global accumulators) or into attributes (aka properties) of vertices/edges.

2. Multi-hop Path Traversal
   Gremlin's design was motivated by the desire to concisely specify multi-hop linear paths as a pipeline of individual traversal step operations.

3. Intermediate Result Flow
   Intermediate results can be transmitted down the pipeline by storage into the traverser object via a variable binding (in the same spirit in which GSQL passes data via accumulators).

4. Control Flow
   Gremlin features both if-then-else style branching and loops, whose guard conditions do not only specify global intermediate results but also data local to the traversers.

5. Query-Calling-Query
   This is supported as Gremlin allows users to define functions that can invoke each other, including recursively.

6. SQL and Turing Completeness
   Gremlin is Turing-complete and thus SQL-complete.

Programming Style

A characteristic of Gremlin is that the attributes (properties) of vertices and edges are modeled as a property graph that needs to be navigated in order to reach the values of properties. To access several attributes, one needs to perform branching navigation in the property graph (from a given vertex or edge, we need to follow one navigation branch to each of its attribute values).

Another characteristic is that its syntax was optimized to concisely express linear (non-branching) path
navigation. Branching navigation is achieved in a verbose way, by binding a variable to the vertex at the branching point, following the side branch in another linear navigation, then jumping back to the branching point to resume following the main branch.

The interaction of these two characteristics leads to convoluted navigation and verbose query expressions in queries that need to simultaneously access various attributes of the same edge/vertex. We illustrate by translating Example 1 to Gremlin.

```gremlin
toys =
    V().hasLabel('Customer').as('c')                               (1)
    .values('name').as('name')                                     (2)
    .outE('Bought').as('b')                                        (3)
    .values('discount').as('disc')                                 (4)
    .select('b')                                                   (5)
    .values('quantity').as('quant')                                (6)
    .select('b')                                                   (7)
    .outV()
    .has('Product', 'category', eq('toy'))                         (9)
    .as('p')                                                      (10)
    .values('price').as('price')                                  (11)
    .select('price', 'disc', 'quant')                              (12)
    .map{it.get().price*(1-it.get().disc/100.0)*it.get().quant}         (13)
    .as('sale_price')                                             (14)
    .select('name','sale_price')                                      (15)
    .group().by('name').by(sum())                                     (16)
```

The above program performs the following steps. (1) Check that the vertex has label ‘Customer’, if so bind variable ‘c’ to it. (2) Go to its ‘name’ attribute, bind variable ‘name’ to it. (3) Go to outgoing ‘Bought’ edge, bind variable ‘b’ to it. (4) Go to value of ‘discount’ property of ‘b’, bind variable ‘disc’. (5) Go back to edge ‘b’. (6) Go to value of b’s property ‘quantity’, bind variable ‘quant’. (7) Go back to edge ‘b’. (8) Go to target vertex of edge ‘b’. (9) Check that it has label ‘Product’, and a property ‘category’ whose value is ‘toy’. (10) Bind variable ‘p’ to this ‘Product’ vertex. (11) Go to the value of the ‘price’ property, bind variable ‘price’ to it. (12) Output tuples of variable bindings with components for the variables ‘price’, ‘disc’, and ‘quant’. (13) For each such tuple, referred to by the built-in variable ‘it’, compute the price per sale by executing the function given as argument to the map. (14) Bind variable ‘sale_price’ to the value computed at step 13. (15) Output tuples of variable bindings with components for the variables ‘name’ and ‘sales_price’. (16) Group these tuples by ‘name’, summing up the ‘sales_price’ column.

Note that the navigation to the values of the ‘price’, ‘discount’, and ‘quantity’ attributes is branching and involves
repeated returns to edge b (e.g., in Lines (6) and (8))

Also note that the ability to bind variables is crucial to expressing this query (and all others in our running example) in Gremlin. Some current systems, such as Amazon’s Neptune, only support variable-free Gremlin expressions (see the user guide), precluding the specification of this kind of query.

Finally, note that translating Example 3 to Gremlin encounters an additional difficulty: like SQL queries, Gremlin queries can group a table by one group-by attribute list or by another, but not simultaneously by both. Therefore, the grouping by category and the grouping by discount performed in Example 3 require a verbose query that defines the same table of variable bindings twice, each followed by its own grouping, and then joins or, more efficiently in terms of result size, unions the two. Contrast this with the ease with which GSQL specifies the simultaneous computation of the two groupings of the same data by simply writing each value into two distinct grouping accumulators (Lines 6 and 7 in Example 3).

Cypher

Cypher is a declarative graph query language based on patterns with variables, such that each pattern match yields a tuple of variable bindings. The collection of these tuples is a relational table that can be manipulated as in SQL.

1. Accumulation

Cypher’s support for accumulation is limited. It supports the collection of data (into lists or tables), and, as in Gremlin, group-by aggregation is computed in SQL style, by defining a relational table and specifying its grouping attributes and aggregated columns. Intermediate results computed during the traversal can be stored into attributes (aka properties) of vertices/edges, but only as long as they are of scalar or list-of-scalar type, since these are the only attribute types in Cypher. In contrast, GSQL can store complex-valued data at vertices (e.g., collections of tuples, be they sets, bags, lists, heaps, or maps) using accumulators.

In particular, the query in Example 3, which needs to store multiple tuples at the customer vertex (one for each category and one for each discount value) has no exact Cypher analogy. For each of the two groupings, the closest approximation would be a Cypher query that, instead of storing the accumulated complex values at each customer vertex, constructs a table that associates the customer vertex’s id with each grouping. This Cypher approximation suffers from another limitation, inherited from SQL: like SQL queries, Cypher queries can group a table by one group-by attribute list or by another, but not simultaneously by both. Therefore, the grouping by category and the grouping by discount require a query that defines the same table of variable bindings twice, each grouped appropriately, and then joins the two.

---

4 Quoting from TinkerPop3 documentation (3/2018): “In previous versions of Gremlin-Groovy, there were numerous syntactic sugars that users could rely on to make their traversals more succinct. Many of these conventions made use of Java reflection and thus, were not performant. In TinkerPop3, these conveniences have been removed in support of the standard Gremlin-Groovy syntax being both in line with Gremlin-Java8 syntax as well as always being the most performant representation. However, for those users that would like to use syntactic sugar at the price of performance loss, there is SugarGremlinPlugin (a.k.a. Gremlin-Groovy-Sugar).” Among the syntactic sugar eliminated in TinkerPop3 is the one allowing the programmer to simply write v.name wherever the value of the name attribute of vertex v is needed, instead of v.values("name").
MATCH (c:Customer) -[b:Bought]-> (p:Product)
WITH c, p.category as cat,
    sum(p.price*(1-b.discount/100.0)*b.quantity) as rev
WITH c, collect({category:cat, revenue:rev}) as byCateg
MATCH (c) -[b:Bought]-> (p:Product)
WITH c, byCateg, b.discount as disc,
    sum(p.price*(1-b.discount/100.0)*b.quantity) as rev
RETURN c, byCateg, collect({discount:disc, revenue:rev}) as byDisc

Contrast this with the ease with which GSQL simultaneously computes the two groupings of the same data by simply writing each value into two distinct grouping accumulators. Note that towards efficient evaluation, Cypher’s optimizer would have to identify the fact that the two MATCH clauses can reuse matches, instead of redundantly recomputing them.

2. Multi-hop Path Traversal
   Cypher can specify multi-hop patterns with variables.

3. Intermediate Result Flow
   Intermediate results can be accessed along the traversal path by referring to the variables bound to them.

4. Control Flow
   Cypher’s control flow includes if-then-else style branching. Loop control is limited, supporting only loops over lists of elements computed prior to the iteration’s start. This can be used to simulate loops of given number of iterations, by first creating a corresponding list of integers: unwind range(1,30) as iter specifies a 30-iteration loop with iteration variable iter and unwind L as e specifies an iteration over the elements of the list L, binding variable e to each.

Recalling the PageRank version that iterates until the maximum error falls below a threshold, note that it relies on loops whose guard condition depends on an intermediate result updated during the iteration. This kind of loop is not supported in Cypher and the corresponding class of algorithms is not expressible (e.g., PageRank is provided as built-in primitive implemented in Java).

5. Query-Calling-Query
   Cypher allows users to define functions but these must be implemented in Java, as per the Neo4j developer manual. This design introduces two drawbacks. First, the programmer must be fluent in both Cypher and Java simultaneously. Second, user-defined functions are black boxes to the neo4j optimizer and therefore cannot be optimized in the context of the calling query.

6. SQL and Turing Completeness
   Cypher is SQL-complete but not Turing-complete. The loop control limitations mentioned above are one of the reasons precluding Turing completeness. This statement ignores arbitrary user-defined functions, whose implementation in Java is allowed by Neo4j, and in whose presence the question becomes
meaningless since Java is Turing-complete.

**SPARQL**

SPARQL is a declarative query language designed for semantic-graph data where connected data is represented in the Resource Description Framework (RDF [https://www.w3.org/RDF/]) format. The primary goal of RDF was to make web pages machine digestible. SPARQL was to enable higher-level querying of the semantic web. Over the time, RDF and SPARQL have been extended to manage a wider range of interconnected data. That being said, SPARQL was not designed for the property graph model (node entities and edge entities, each with characteristic attributes).

RDF defines data in terms of triples: `<subject><predicate><object>`. One triple describes the relationship between two entities or the relationship between an entity and one of its attributes. Each triple can be thought of as an edge in a graph: `<source_vertex><edge><target_vertex>`, thus an RDF dataset is a graph. Consider the following triple: `<John Smith><teacherOf><Calculus>`. “John Smith” and “Calculus” are the subject and object, respectively. “teacherOf” is the predicate indicating their relationship. Consider another triple `<John Smith><gender><Male>`. “John Smith” is the subject, and “Male” is his attribute. The predicate “gender” describes the relationship between the subject and its attribute.

SPARQL syntax borrows many keyword and design philosophies from SQL. For example,

```sparql
SELECT ?title
WHERE
{
}
```

Just as in SQL, SELECT projects a set of expressions from the underlying data set (triple store). The WHERE clause holds a list of graph patterns in triple or path format. The user may use ? or $ in the subject or the object position to ask for matches and to bind variables to those positions.

1. **Accumulation**

   SPARQL has aggregation operators COUNT, SUM, etc. and a GROUP BY clause as found in SQL. A query can select a select of triples and then aggregate them. One approach is to define a named graph to store intermediate results. This is similar to Cypher’s WITH clause and VIEW concept in SQL. Then, the user can select from the named graph in the FROM clause. The limitations and differences from GSQL are the same as the discussion in Cypher. Example:

```sparql
CREATE GRAPH <urn:example/g/g1>
INSERT {
```
2. Multi-hop Path Traversal

SPARQL can specify multi-hop patterns by stating a set of triples which connect to one another via common variables. In the example below, we have 2-hop path ?title—<title>—?book—<price>—?price. It selects the titles of all books which have a price. Using multiple triples is similar to a GSQL query having multiple SELECT blocks, each describing one hop. The SPARQL syntax is more compact, but the GSQL structure makes it easier to customize the actions of each hop.

```sparql
SELECT ?title
WHERE
{
}
```

3. Intermediate Result Flow

Intermediate results can be accessed via (1) a named graph (similar to a materialized view in a relational database) in the FROM clause by referring to the variables bound to them, or (2) a subquery. Due to the bottom-up nature of SPARQL query evaluation, the subqueries are evaluated logically first, and the results are projected up to the outer query.

4. Control Flow

SPARQL (as of version 1.1) does not support iterative flow control. The user must resort to an external host language (such as JavaScript) to construct loops.

5. Query-Calling-Query

SPARQL grammar allows users to define functions, and plug those functions into the WHERE clause pattern. However, it does not natively support named stored procedure that can be called by another query.

6. SQL and Turing Completeness

SPARQL is SQL-complete but not Turing-complete⁵. The loop control limitations mentioned above are one of the reasons precluding Turing completeness.

⁵ “The Expressive Power of SPARQL” https://dl.acm.org/citation.cfm?id=1483165
Final Remarks

There is one more feature of GSQL that sets it apart from other graph query languages, which enables better query optimization as well as added security.

GSQL assumes a predefined schema, which is stored as metadata in the database catalog. This improves storage and access efficiency, because the schema metadata can be factored out of the vertex/edge/attribute representation. This leads to increased performance not only due to space savings but also because queries can be optimized to a greater degree when a deeper understanding of the data model is known in advance: more filtering, better ordering, more shortcuts, etc. Exploiting pre-defined schemas at optimization time is a tried-and-true database technique that has time and again led to better performance.

Additionally, the pre-defined schema is exploited for security and privacy purposes to provide graph schema-aware access control. GSQL’s MultiGraph feature allows an unlimited number of subgraph schemas to be defined within the global schema, and then it enhances traditional role-based access control by using subgraph name as an additional factor for granting privileges. This functionality is critical in real-life applications as it enables multiple tenants (e.g., multiple departments of a company) to use the same graph database with distinct access permissions. This is the industry’s first and only such support so far.

GSQL matches or surpasses the expressive power of other graph query languages. While the underlying programming paradigm is a matter of taste, GSQL has been designed for compatibility with both SQL and NoSQL’s Map-Reduce programming paradigm, thus appealing to both programmer communities.
Chapter 10

Real-Time Deep Link Analytics in the Real World

As the first and only native parallel graph database with real-time deep link analytics capability, TigerGraph is uniquely qualified to solve some of today’s business challenges. In this chapter, we examine several real-world use cases and show how real-time deep link analytics is now providing real solutions and real business value.

Combating Fraud and Money Laundering with Graph Analytics

Dirty money and money laundering have been around since the existence of currency itself. On a global level, as much as $2 billion is washed annually, estimates the United Nations⁶. Today’s criminals are sophisticated, using ever-adapting tactics to bypass traditional anti-fraud solutions. Even in cases where enterprises do have enough data to reveal illicit activity, more often than not they are unable to conduct analysis to uncover it.

As the fight against money laundering continues, AML (anti money laundering) compliance has become big business. Global spending in AML alone weighs in at more than $8 billion, says WealthInsight\(^7\). This figure will continue to grow, considering how any organization facilitating financial transactions also falls within the scope of AML legislation.

But combating crime is never easy. Especially when organizations face pressing needs for cost reduction and faster time to AML compliance in order to avoid regulatory fees. Legacy monitoring systems have proven burdensome and expensive to tune, validate and maintain. Often involving manual processes, they are generally incapable of analyzing massive volumes of customer, institution, and transaction data. Yet it is this type of data analysis that is so critical to AML success.

New ideas have emerged to tackle the AML challenge. These include semi-supervised learning methods, deep learning based approaches, and network/graph based solutions. Such approaches must be able to work in real time and handle large data volumes – especially as new data are generated 24/7. That’s why a holistic data strategy is best for combating financial crime, particularly with machine learning (ML) and AI to help link and analyze data connections.

**Graph Analytics for AML**

Graph analytics has emerged at the forefront as an ideal technology to support AML. Graphs overcome the challenge of uncovering the relationships in massive, complex, and interconnected data. The graph model is designed from the ground up to treat relationships as first-class citizens. This provides a structure that natively embraces and maps data relationships, even in high volumes of highly connected data. Conducted over such interconnected data, graph analytics provides maximum insight into data connections and relationships.

For example, “Degree Centrality” provides the number of links going in or out of each entity. This metric gives a count of how many direct connections each entity has to other entities within the network. This is particularly helpful for finding the most connected accounts or entities which are likely acting as a hub, and connecting to a wider network.

Another is “Betweenness,” which gives the number of times an entity falls on the shortest path between other entities. This metric shows which entity acts as a bridge between other entities. Betweenness can be the starting point to detect any money laundering or suspicious activities.

Today’s organizations need real-time graph analytic capabilities that can explore, discover, and predict very complex relationships. This represents Real-Time Deep Link Analytics, achieved utilizing three to 10+ hops of traversal across a big graph, along with fast graph traversal speed and data updates.

Let’s take a look at how Real-Time Deep Link Analytics combats financial crime by identifying high-risk transactions. We’ll start with an incoming credit card transaction, and demonstrate how this transaction is

\(^7\) [https://www.marketresearch.com/product/sample-7717318.pdf](https://www.marketresearch.com/product/sample-7717318.pdf)
related to other entities can be identified:

<table>
<thead>
<tr>
<th>Transaction</th>
<th>Card</th>
<th>Cardholder</th>
<th>Other Cards</th>
<th>Other</th>
</tr>
</thead>
<tbody>
<tr>
<td>New</td>
<td>Credit Card</td>
<td>Cardholder</td>
<td>(other) Credit Cards</td>
<td>(other)</td>
</tr>
<tr>
<td>Bad Transactions</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

This query uses four hops to find connections only one card away from the incoming transaction. Today's fraudsters try to disguise their activity by having circuitous connections between themselves and known bad activity or bad actors. Any individual connecting the path can appear innocent, but if multiple paths from A to B can be found, the likelihood of fraud increases.

Given this, successful anti-money laundering requires the ability to traverse several hops. This traversal pattern applies to many other use cases — where you can simply replace the transaction with a web click event, a phone call record, or a money transfer. With Real-Time Deep Link Analytics, multiple, hidden connections are uncovered and fraud is minimized.

By linking data together, Real-Time Deep Link Analytics can support rules-based ML methods in real time to automate AML processes and reduce false positives. Using a graph engine to incorporate sophisticated data science techniques such as automated data flow analysis, social network analysis, and ML in their AML process, enterprises can improve money laundering detection rates with better data, faster. They can also move away from cumbersome transactional processes, and towards a more strategic and efficient AML approach.

**Example: E-payment Company**

For one example of graph analytics powering AML, we can look towards the #1 e-payment company in the world. Currently this organization has more than 100 million daily active users, and uses graph analytics to modernize its investigation methods.

Previously, the company’s AML practice was a very manual effort, as investigators were involved with everything from examining data to identifying suspicious money movement behavior. Operating expenses were high and the process was highly error-prone.

Implementing a graph analytics platform, the company was able to automate development of intelligent AML queries, using a real-time response feed leveraging ML. Results included a high economic return using a more effective AML process, reducing false positives and translating into higher detection rates.

**Example: Credit Card Company**

Similarly, a top five payment provider sought to improve its AML capabilities. Key pain points include high cost and inability to comply with federal AML regulations — resulting in penalties. The organization relied on a manual investigative process performed by a ML team comprised of hundreds of investigators, resulting in a slow, costly and inefficient process with more than 90 percent false positives.

The company currently is leveraging a graph engine to modernize its investigative process. It has moved from
having its ML team cobble processes together towards combining the power of graph analytics with ML to provide insight into connections between individuals, accounts, companies and locations.

By uniting more dimensions of its data, and integrating additional points – such as external information about customers – it is able to automatically monitor for potential money laundering in real time, freeing up investigators to make more strategic use of their now-richer data. The result is a holistic and insightful look at its colossal amounts of data, producing fewer false positive alerts.

As we continue into an era of data explosion, it is more and more important for organizations to make the most in analyzing their colossal amounts of data in real time for AML. Graph analytics offers overwhelming potential for organizations in terms of cost reduction, in faster time to AML compliance and most importantly, in their ability to stop money laundering fraudsters in their tracks.

How Graph Analytics Is Powering E-commerce

We have entered an era where e-Commerce rules retail. Consider how reports project online sales to hit more than $4 trillion by 2020, representing 14.6% of total retail spending worldwide (source: eMarketer⁸). Over the past few years, online shopping has transformed how we buy, bringing in a new “Age of the Consumer.” Today, shoppers have access to more information than ever around products and brands, all informing their purchasing decisions. They also are taking the lead in their own online shopping experiences, with the global marketplace available at their fingertips.

⁸ https://www.emarketer.com/Article/Worldwide-Retail-Ecommerce-Sales-Will-Reach-1915-Trillion-This-Year/1014369
In turn, e-Commerce has embraced AI-powered assistants, recommendation engines, and even automated platforms to help consumers consider what to evaluate and buy. Insights generated from AI platforms provide tremendous value, and can potentially drive further revenues for companies, as well as provide shoppers with a better, more customized customer experience.

Traditional brick-and-mortar sales relied, and continue to rely, on establishing a connection with the customer in the form of discerning and evaluating their needs, making recommendations and walking them through the sales process. Connections matter even more so when it comes to online sales, as the most successful retailers today offer a customer-centric e-Commerce platform. This involves a consistent multipath purchase experience, achieved through a 360-degree view of each and every customer. Being able to translate customer data and activity into actionable intelligence to support the customer during their shopping experience with product recommendations and more can lead to increased conversions and higher units per transaction.

The key to successfully leveraging this data is having it and being able to analyze it effectively in the first place, not to mention being able to do so in real time, during a customer’s live shopping session. Most e-Commerce retailers are able to gather the data, but are finding that traditional analytic solutions are missing the mark to achieve this. Historically, solutions have been too slow or expensive, and often are incapable of deriving sophisticated insight from massive amounts of customer, transaction, and external data.

Real-time offers — be it products on hand, conditional promotions or free shipping to save a sale — require knowing your customers, and knowing them well. This means e-Commerce sites need to collect and leverage consumer segmentation data as quickly as possible to provide targeted recommendations and customer service. The result is being able to offer a more personalized shopping experience that customers enjoy, engage with, and consistently come back to for their needs.

**Delivering a Better Online Shopping Experience...And Driving Revenue**

Achieving this is no easy feat, especially using traditional databases that tend to store data in tables. That’s why more and more retailers are turning to the power of graph database technology to support real-time analytics and more. For retail, graph databases are the ideal choice for an industry where connections are of the utmost essence. This is because graph databases are designed from the ground up to treat relationships as first-class citizens, providing a structure natively embracing the relationships between data. This ensures better storing, processing and querying of connections than ever before.

For example, consider a simple personalized recommendation such as “customers who liked what you liked also bought these items.” Starting from a person, a query made in a graph database first identifies items viewed/liked/bought. Second, it finds other people who have viewed/liked/bought those items. Third, it identifies additional items bought by those people.

Person → Product → (other)Persons → (other) Products
To power such queries, over the past few years graph databases have seen a major uptick in enterprise adoption, particularly by retailers powering e-Commerce sites. While the first generation of graph database solutions have been helpful in addressing the e-Commerce data problem, they are not without their limitations. Query speeds and analysis of data are relatively slow, with graph engines only able to support traversals (the process of visiting, or checking and/or updating, points of data) to a certain extent. Deeper traversals allow you to glean better insights from data.

Empowering E-Commerce with Real-Time Deep Link Analytics

Recently, we have seen the next phase in the graph database evolution, with technology fulfilling the needs of e-Commerce by providing Deep Link Analytics. This enables customer intelligence in real time, along with powerful relationship analysis. With these real-time capabilities, e-Commerce sites can quickly synthesize and make sense of customer behavior. The result is the capture of key Business Moments, transient opportunities where people, businesses, data, and “things” work together dynamically to create value used to personalize the customer experience, which leads to more transactions.

This is accomplished as new graph database technology supports 10+ hops (or traversals of data points as described above), unlike being limited to just two as first-generation solutions are. Each hop adds more intelligence about an individual user’s shopping history — whether it is their first visit or they are a repeat customer. Analyzing the data/product/customer location/weather based on location/recommended products requires the capability to traverse the data to present a recommendation in real time.

The query above requires three hops in real time, so it is beyond the two-hop limitation of current-generation graph technology on larger data sets. Adding in another relationship easily extends the query to four or more hops. This data continuously feeds the AI and machine learning algorithms designed to bring a better online shopping experience.

Deep Link Analytics allow e-Commerce companies to be able to traverse these data, creating smarter AI and machine learning to deliver competitive advantages, close more deals, and build customer loyalty. It all comes down to being able to derive better insight by considering more connections among your data to adequately address a shopper’s online behavior and preferences.

Deep Link Analytics for Product Recommendations

Example: Mobile E-Commerce Company

Let’s consider an example of Deep Link Analytics being used by a retailer today. A major global e-Commerce platform uses Deep Link Analytics to model its vast product catalog, map its consumer entity data, and to perform real-time analytics over its complex and colossal amounts of data. This leads to real-time recommendations that
are personalized for each shopper, driving sales and revenue.

At a technical level, the solution has increased query speeds by 100x compared to the company's previous in-house solution, with query responses in under 100 milliseconds. It also has saved memory usage by 10x, achieved through efficient graph-based encoding and compression. As fewer machines are needed, this also has helped cut hardware management and maintenance costs.

Data scientists and machine learning experts are able to do more, faster, as they are able to use a single massive graph integrating all the company's connected data. The business derives insight from its massive amounts of data to support better decision making and improving time to market. The graph database platform also provides the speed and scalability needed to make the most data relationships for competitive advantage.

The Customer Connection

Retailers are finding that connecting with consumers online is just as important as connecting with them in person when they shop in a brick-and-mortar location. To achieve this, it has become more and more relevant for e-Commerce to find ways to scan through huge amounts of data and to make sense of it.

Today, it's more possible to do this than ever before, especially using a graph database where connections among data are at the forefront. As graph databases mature, they are powering deeper insight by supporting queries over more connected data. Customers enjoy a better shopping experience, while retailers benefit from happier and more engaged shoppers along with additional sales and revenues.

Electric Power System Modernization

Creating a faster-than-real-time Energy Management System (EMS) is a huge challenge for the power industry. Faster-than-real-time means the EMS must be capable of completing execution within a Supervisory control and data acquisition (SCADA) sample cycle, typically 5 seconds.

Faster-than-real-time EMS capability is key to maintaining awareness over power system events, helping prevent power system blackouts from occurring. For over a decade, power system engineers have been unsuccessful at developing faster EMS applications for large-scale power systems. If achieved, it would help operators in control centers to make power system operations more secure and cost-effective. So far, no commercial EMS had been able to perform at such faster-than-real-time levels.

Technical challenges to curb EMS application computation efficiency include: A) The power system becoming larger and larger to meet growing demand, B) High renewable energy penetration, FACTS devices, and HVDC transmission lines making power system models more complex, and C) Rapid fluctuations in power demand and supply combined with fast-response devices leading to more frequent and intensive recalculations.
Parallel computing is a breakthrough solution for speeding up EMS applications. Power system engineers have investigated different parallel computing approaches based on relational database structure to improve the EMS application computing efficiency, but until now have been unable to achieve faster-than-real-time EMS.

Example: National Utility Company

Using TigerGraph’s native parallel graph database, with node-as-a-compute-engine design, State Grid Corporation of China (SGCC) has achieved a faster-than-real-time EMS prototype, verified by provincial power system cases.

Conventionally, power systems are modeled using relational databases in a collection of interlinked tables. As different components of power systems are stored in separate tables, they need to be linked together using shared key values to model the connectivity and topology of the power system. Connecting or linking across separate tables (database joins) takes about 25% of the total processing time for power flow calculation and 35% for power grid state estimation, according to the results of the case study.

The standard approach of solving large-scale linear equations requires bulky, time-intensive matrix operations. Modeling a power system as a graph (instead of a matrix) represents connections and topology more naturally. No data preparation is needed, cutting 25-35% of the generally required time for power flow calculation and state estimation. Bus ordering and admittance graph formation are performed in nodal parallel (with all nodes computing at the same time to ensure the ordering sequence and admittance graph are in parallel). Symbolic and numerical factorization and forward/backward substitution are performed in hierarchical parallel, with nodes partitioned into levels. Nodes at the same level are calculated in parallel, starting with the lowest level. Core calculations are all conducted on graph, and solved values are stored as attributes of vertices and edges of the graph — rather than unknown variables in the vector or matrix.

In the conventional approach, power system problems are solved as unknown variables and assigned to the X vector. To visualize the solved value, a mapping process is used to link the unknown variable to displays.

Using TigerGraph, solved values are stored as attributes of vertices and edges on a graph — forgoing the need for a mapping process. According to the test case, output visualization takes about 70% of total time for power flow calculation, and 28% for state estimation when using the conventional approach. Using TigerGraph graph database and graph computing, that portion of the time is eliminated.

This table summarizes test results of the faster-than-real-time EMS comparing with D5000, the widely used commercial EMS covering most control centers in China and many other countries.
The total execution time of the three major EMS applications — State Estimation, Power Flow, and Contingency Analysis — is a little above 1 second combined, which is much less than the SCADA sample cycle standard of 5 seconds. With the help of TigerGraph, State Grid of China has achieved the first viable faster-than-real-time EMS solution for commercial use.

Faster than real-time Energy Management System (EMS) has been the holy grail for power management especially as any power outages directly affect the productivity and economic output / GDP (Gross Domestic Product) of the nation. Such a system can identify mismatches between power demand and supply, lower power consumption for non-critical parts of the grid, and divert power to higher priority areas for industrial output and national security and be able to accomplish all of this in under one second.

<table>
<thead>
<tr>
<th>Test System</th>
<th>State Estimation</th>
<th>Power Flow</th>
<th>Contingency Analysis</th>
</tr>
</thead>
<tbody>
<tr>
<td>Commercial EMS</td>
<td>4488 ms</td>
<td>3817 ms</td>
<td>18000 ms</td>
</tr>
<tr>
<td>TigerGraph Based EMS Prototype</td>
<td>172 ms</td>
<td>79 ms</td>
<td>772 ms</td>
</tr>
</tbody>
</table>
Chapter 11

Graphs and Machine Learning

Fraud detection, in many ways, resembles finding needles in a haystack. You must sort and make sense of massive amounts of data in order to find your "needles" or in this case, your fraudsters.

Let’s use the example of a phone company with billions of calls occurring in its network, all on a weekly basis. How can it identify signs of fraudulent activity from its mountain — or haystack — of call logs? This is where machine learning provides value, offering a magnet, which in this case, is the ability to identify behaviors and patterns of likely fraudsters. Using a graph model, a machine becomes more adept at recognizing suspicious phone call patterns and is able to separate them from the billions of calls made by regular people which comprises our haystack of data.

Indeed, more and more organizations are leveraging machine learning, along with graphs, to prevent various types of fraud, including phone scam, credit card chargeback, advertising, money laundering, and more. Before we further discuss the value of the powerful combination of machine learning and graphs, let’s take a look at how current approaches for identifying fraudsters based on machine learning are missing the mark.

A Machine Learning Algorithm Is Only as Good as Its Training Data

In order to detect a specific condition, such as a phone engaged in a scam or a payment transaction involved in money laundering, a machine learning system requires sufficient volume of fraudulent calls or payment transactions that are likely to be related to money laundering. Let’s drill down further with using phone-based fraud as an example.

In addition to the volume of calls that are likely to be fraudulent, a machine learning algorithm also requires features or attributes that have a high correlation with the phone fraud behavior.

As fraud (much like money laundering) is part of less than 0.01 percent or 1 in 10,000 of the total volume of transactions, the volume or the quantity of training data with confirmed fraud activity is very small. Having such a limited quantity of training data, in turn, results in poor accuracy for the machine learning algorithms.

It is simple to select some features or attributes which correlate to fraud. In the case of phone-based fraud, they include calling history of particular phones to other phones that may be in or out of the network, the age of a prepaid SIM card, percentage of one-directional calls made (cases where the call recipient did not return a phone call), and the percentage of rejected calls. Similarly, to find payment transactions involved in money laundering, features such as size and frequency of the payment transactions are fed into the machine learning system.

However, by relying on features focused on individual nodes alone, the result is a high rate of false positives. For
example, a phone involved in frequent one-directional calls may belong to a sales representative, who is calling prospects to find leads or sell goods and services. It may also be involved in harassment, where one user is calling another as a prank. A high volume of false positives results in a wasted effort to investigate non-fraudulent phones, leading to low confidence in a machine learning solution for fraud detection.

More Data Beats Better Algorithms

There's a popular saying in machine learning - “more data beats better algorithms”. A large number of machine learning fail due to lack of sufficient quantity of training data. To put it simply, sample size directly affects the quality of prediction. Anomaly detection events such as fraud, money laundering or cyber security breaches have a small number of confirmed events compared to the massive volume of transactions - orders, payments, phone calls and machine access logs.

TigerGraph is used by multiple large customers from Uber, Alipay to Wish.com and China Mobile, to compute graph based attributes or features in machine learning lingo. In case of China Mobile, TigerGraph generates 118 new features per phone for each of their 600 million phones. This creates over 70 Billion new features to separate the “bad phones” - those with suspected fraud activity from the rest of the “good phones” belonging to regular customers. In case of China Mobile, more training data - 70 Billion features are generated and fed to machine learning solution to improve accuracy of fraud detection.

Building a Better Magnet for Phone-Based Fraud

Real-life examples are proving the value of graphs and machine learning to combat fraud. Currently, a large mobile operator uses a next-generation graph database with real-time deep link analytics, to address the deficiencies of current approaches for training machine learning algorithms. The solution analyzes over 15 billion calls for 600 million mobile phones and generates 118 features for each mobile phone. These are based on deeper analysis of calling history and go beyond immediate recipients for calls.

The diagram below illustrates how the graph database identifies a phone as a “good” or a “bad” phone. The graph database solution also identifies what type of fraud is suspected (e.g., spam ad, scam sales, etc.) and displays a warning message on the callee’s phone, all while the phone is still ringing.
Figure 1 – Detecting phone-based fraud by analyzing network or graph relationship features

A customer with a good phone calls other subscribers, and the majority of their calls are returned. This helps to indicate familiarity or trusted relationships between the users. A good phone also regularly calls a set of other phones — say, every day or month — and this group of phones is fairly stable over a period of time (“Stable Group”).

Another feature indicating good phone behavior is when a phone calls another that has been in the network for many months or years and receives calls back. We also see a high number of calls between the good phone, the long-term phone contact and other phones within a network calling both these numbers frequently. This indicates many in-group connections for our good phone.

Lastly, a “good phone” is often involved in a three-step friend connection — meaning our good phone calls another phone, phone two, which calls phone three. The good phone is also in touch with direct calls with phone three. This indicates a three-step friend connection, indicating a circle of trust and interconnectedness.

By analyzing such call patterns between phones, our graph solution can easily identify bad phones, which are phones likely involved with the scam. These phones have short calls with multiple good phones, but receive no calls back. They also do not have a stable group of phones called on a regular basis (representing an “empty stable group”). When a bad phone calls a long-term customer in the network, the call is not returned. The bad phone also receives many rejected calls and lacks three-step friend relationships.

The graph database platform leverages more than 100 graph features such as Stable Group that highly correlate with good and bad phone behavior for each of 600 million mobile phones in our use case. In turn, it generates 70 billion new training data features to feed machine learning algorithms. The result is improved accuracy of machine learning for fraud detection, with fewer false positives (i.e., non-fraudulent phones marked as potential fraudster
phones) as well as lower false negatives (i.e., phones involved in fraud that weren’t marked as such).

To see how graph-based features improve accuracy for machine learning, let’s consider an example (Figure 2) using profiles for four mobile users: Tim, Sarah, Fred and John.

<table>
<thead>
<tr>
<th></th>
<th>Prankster</th>
<th>Regular Customer</th>
<th>Fraudster</th>
<th>Sales</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Age of sim card</strong></td>
<td>2 weeks</td>
<td>4 weeks</td>
<td>3 weeks</td>
<td>2 weeks</td>
</tr>
<tr>
<td><strong>% of one directional calls</strong></td>
<td>50%</td>
<td>10%</td>
<td>55%</td>
<td>60%</td>
</tr>
<tr>
<td><strong>% rejected calls</strong></td>
<td>40%</td>
<td>5%</td>
<td>28%</td>
<td>25%</td>
</tr>
<tr>
<td><strong>Prediction by ML with call history features</strong></td>
<td>Likely Fraudster</td>
<td>Regular Customer</td>
<td>Likely Fraudster</td>
<td>Likely Fraudster</td>
</tr>
<tr>
<td><strong>Stable group</strong></td>
<td>Yes</td>
<td>Yes</td>
<td>No</td>
<td>No</td>
</tr>
<tr>
<td><strong>Many in-group connections</strong></td>
<td>No</td>
<td>Yes</td>
<td>No</td>
<td>Yes</td>
</tr>
<tr>
<td><strong>3-step friend relation</strong></td>
<td>No</td>
<td>Yes</td>
<td>No</td>
<td>Yes</td>
</tr>
<tr>
<td><strong>Prediction by ML with deep link Graph features</strong></td>
<td>Likely Prankster</td>
<td>Regular Customer</td>
<td>Likely Fraudster</td>
<td>Likely Sales</td>
</tr>
</tbody>
</table>

**Figure 2 – Improving accuracy for machine learning with graph features**

Traditional calling history features, such as the age of the SIM card used, percentage of one-directional calls and percentage of total calls rejected by their recipients, result in flagging three out of four of our customers, Tim, Fred and John as likely or potential fraudsters as they look very similar based on these features. Graph-based features with analysis of deep link or multi-hop relationships across phones and subscribers help machine learning classify Tim as a prankster, John as a salesperson, while Fred is flagged as a likely fraudster. Let’s consider how.

In the case of Tim, he has a stable group, which means he is unlikely to be a sales guy since salespeople call different numbers each week. Tim doesn’t have many in-group connections, which means he is likely calling strangers. He also doesn’t have any three-step friend connections to confirm that the strangers he is calling aren’t related. It is very likely that Tim is a prankster based on these features.

Let’s consider John who doesn’t have a stable group, which means he is calling new potential leads every day. He calls people with many in-group connections. As John presents his product or service, some of the call recipients are most likely introducing him to other contacts if they think the product or service would be interesting or relevant to them. John is also connected via three-step friend relations, indicating that he is closing the loop as an effective sales guy, navigating the friends or colleagues of his first contact within a group, as he reaches the final buyer for his product or service. The combination of these features classifies John as a salesperson.

In the case of Fred, he doesn’t have a stable group, nor does he interact with a group that has many in-group connections. Plus, he does not have three-step friend relations among the people he calls. This makes him a very
likely candidate for investigation as a phone scam artist or fraudster.

Going back to our original analogy, we are able to find our needle in the haystack, in our case, it's Fred the potential fraudster, by leveraging graph analysis for better machine learning for improved accuracy. This is achieved by using the graph database framework to model data in a way that allows for more features that can be identified and considered to further analyze our haystack of data. The machine, in turn, is trained with more and more accurate data, making it smarter and more successful in recognizing potential scam artists and fraudsters.

**Building a Better Magnet for Anti-Money Laundering**

Graphs and machine learning are used for a host of fraud detection use cases beyond identifying a phone-based scam. Machine learning algorithms are being trained to detect various other types of anomalous behavior, such as identifying potential money laundering.

Global money laundering transactions comprise an estimated two to five percent of the global GDP, or roughly $1 to 2 trillion annually, according to a PWC report. The risk of money laundering spans the entire financial services ecosystem and including banks, payment providers, and newer cryptocurrencies, such as Bitcoin and Ripple. Given how much financial activity occurs every second of every day, how is it possible to find the needles — our fraudsters, in a haystack of data?

Traditional rule-based approaches focus on attributes or features for the individual node such as payment or user in question, but this often leads to high volumes of false positives. The same data can be fed into a machine learning algorithm, resulting in a poor accuracy of future fraud prediction by the machine learning system — poor data in, poor insights out!

As you can expect, fraudsters disguise their activity with circuitous connections between themselves and known bad activity or bad actors. This is where graphs offers value — by identifying and finding features over data connections and relationships that can be used to better inform and train machine learning. These features may include size and frequency of the payment transactions or they may be more abstractly based on relationships between the data.

For example, a graph-based approach can uncover semantically meaningful connecting paths between nodes. Let's consider an incoming credit card transaction to show how its relation to other entities can be identified:

```
New Transaction → Credit Card → Cardholder → (other)Credit Cards → (other)Bad Transactions
```

This query uses four hops to find connections only one card away from the incoming transaction. Any individual connecting the path can appear innocent, but if multiple paths from A to B can be found, the likelihood of fraud increases. Given this, successful anti-money laundering requires the ability to traverse several hops. In this way, Real-Time Deep Link Analytics offers value in uncovering multiple, hidden connections to minimize money
Second, a graph-powered approach enables the use of graph-based statistics to measure the global relevance of nodes, links, and paths. For example, the feature of betweenness gives the number of times an entity falls on the shortest path between other entities. This metric shows which entity acts as a bridge between other entities. Betweenness can be the starting point to detect any money laundering or suspicious activities. A high betweenness score could indicate that someone or something is a go-between in a fraud ring or in money laundering layering.

Similarly, other graph-based analytics, such as degree centrality and community detection, can add necessary coloring to otherwise unremarkable data points. Degree centrality provides the number of links going in or out of each entity, offering a count of how many direct connections each entity has to other entities within the network. This is particularly helpful for finding the most connected accounts or entities which are likely acting as a hub, and connecting to a wider network. Community detection finds the natural groupings in a network, by comparing the relative density of in-group connections vs. between-group connections. A person who is in the same small community with known criminals may be more likely to be a criminal. By linking data together, graph analytics can support rules-based machine learning methods in real time to automate automated money laundering (AML) processes and reduce false positives. Using a graph engine to incorporate sophisticated data science techniques such as automated data flow analysis, social network analysis, and machine learning in their AML process, enterprises can improve money laundering detection rates with better data, faster. They can also move away from cumbersome transactional processes, and towards a more strategic and efficient AML approach.

Example: E-payment Company

For one example of graphs and machine learning powering AML, we can look towards the #1 e-payment company in the world. Currently, this organization has more than 100 million daily active users, and uses graph analytics to modernize its investigation methods.

Previously, the company’s AML practice was a very manual effort, as investigators were involved with everything from examining data to identifying suspicious money movement behavior. Operating expenses were high and the process was highly error-prone.

Implementing graph analytics, the company was able to automate development of intelligent AML queries, using a real-time response feed leveraging machine learning. Results included a high economic return using a more effective AML process, reducing false positives and translating into higher detection rates.

Example: Credit Card Company

Similarly, a top five payment provider sought to improve its AML capabilities. Key pain points include high cost and inability to comply with federal AML regulations — resulting in penalties. The organization relied on a manual
investigative process performed by a machine learning team comprised of hundreds of investigators, resulting in a slow, costly and inefficient process with more than 90 percent false positives.

The company has leveraged a graph engine to modernize its investigative process. It has moved from having its machine learning team cobble processes together towards combining the power of graph analytics with ML to provide insight into connections between individuals, accounts, companies and locations.

By uniting more dimensions of its data, and integrating additional points — such as external information about customers — it is able to automatically monitor for potential money laundering in real time, freeing up investigators to make more strategic use of their now-richer data. The result is a holistic and insightful look at its colossal amounts of data, producing fewer false positive alerts.
Conclusion

In today’s era of data explosion, it’s more and more important for organizations to make the most of analyzing their colossal amounts of data in real time for fraud detection. The powerful combination of graphs with machine learning offers immense value in ensuring that machine algorithms are being fed quality data. As machine training become more effective, the result is more fraudulent activity being identified as it happens. Graphs are a powerful asset in helping to ensure that higher quality, more complex features can be identified to support accurate machine learning designed to find the needles in the haystacks.